System Simulation with gem5, SystemC and other Tools

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Detailed Description of Contents for this Talk

System Simulation with gem5 and SystemC

The Keystone for Full Interoperability

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***Abstract*—SystemC TLM based virtual prototypes have become the main tool in industry and research for concurrent hardware and software development, as well as hardware design space exploration. However, there exists a lack of accurate, free, changeable and realistic SystemC models of modern CPUs. Therefore, many researchers use the cycle accurate open source system simulator gem5, which has been developed in parallel to the SystemC standard. In this paper we present a coupling of gem5 with SystemC that offers full interoperability between both simulation frameworks, and therefore enables a huge set of possibilities for system level design space exploration. Furthermore, we show that the coupling itself only induces a relatively small overhead to the total execution time of the simulation.**

I. Introduction

Today's companies have to deal with complex hardware architectures such as multi-cores, sophisticated interconnects and memory systems. *Virtual Prototypes* (VPs) are widely used to allow for early design space exploration and to decrease the *Time-to-Market* (TTM), costs, and efforts by developing software and hardware concurrently. They are high-speed, fully functional software models of physical hardware systems that can simulate the exact behavior of real hardware. With their help, complete *Multi-Processor System-on-Chips* (MPSoCs) can be simulated with reasonable simulation speed and visibility and controllability over the entire system. Case studies have shown that by employing VPs it is possible to deliver more competitive products up to six months earlier [1].

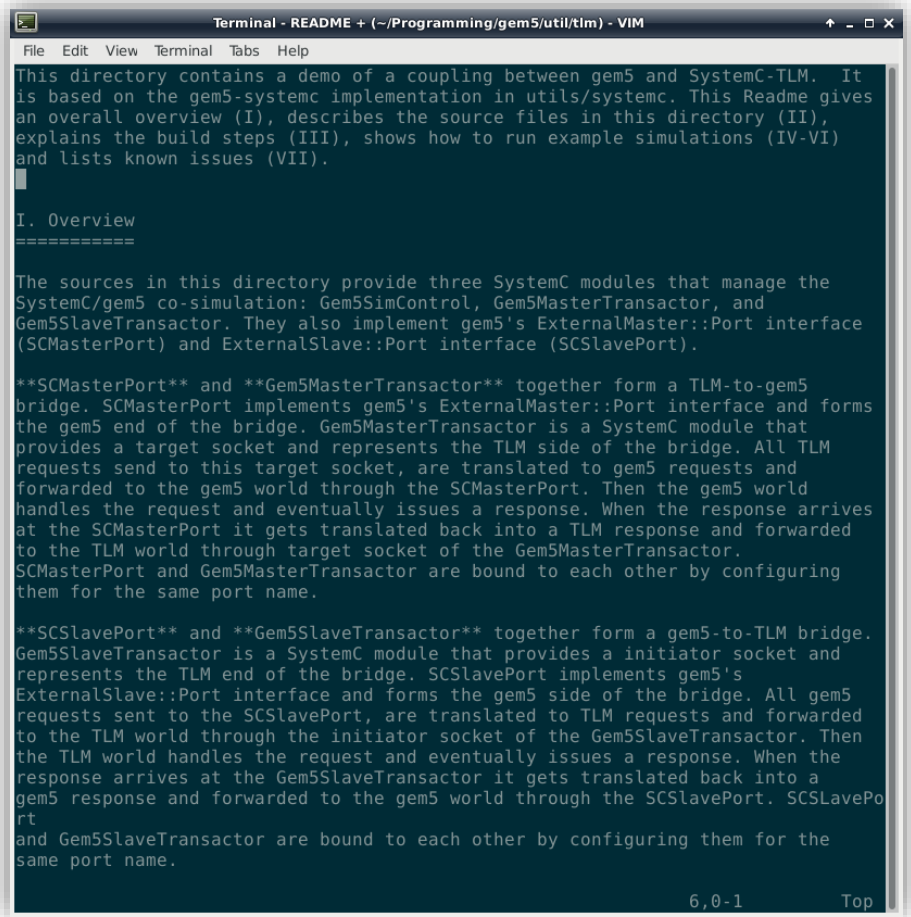
In recent years, the SystemC TLM2.0 IEEE1666 standard [2] has become the main developing tool for VPs in industry and research. It allows to quickly simulate HW and SW systems on different levels of abstraction in order to estimate and optimize the performance and power for different applications. In contrast to pin accurate models, *Transaction Level Modeling* (TLM) abstracts the communication mechanisms from the actual hardware. It encapsulates communication between interacting components in so-called transactions, which are transferred by function calls.

The industry offers several SystemC based CPU core models that provide a trade-off between simulation speed and accuracy. For instance, the *FastModels*, distributed by ARM Ldt. or the OVP [3] models use *just-in-time-compilation* for code execution and model communication using the TLM *loosely-timed* coding style. However, loosely-timed models do not reflect a realistic timing behavior and thus can mainly be used for software development and high level explorations. Cycle accurate simulations can be performed with the commercially available Carbon models from ARM or the Aurix [4] TLM models from Infineon. However, these models are shipped as binary libraries, which makes them useless for micro-architectural research due to their inflexibility (i.e. they cannot be modified). Furthermore, they are slow and can, therefore, not be employed for fast design space exploration.

Figure 1: Possible scenarios for binding gem5 and SystemC:

In contrast to industry, the academia lacks free, accurate and realistic SystemC models of modern CPUs. The most mature cycle accurate open source system simulator is the *gem5* framework, which is a modular platform for computer-system architecture research [5]. It is not only widely used in academia, but also the industry employs gem5 for research. For instance, ARM and AMD use gem5 internally for design space exploration and actively contribute to the open source project. However, gem5 is not implemented in SystemC as its development started before the IEEE ratified the official SystemC and TLM standard in 2005 [2]. Since this time, both frameworks, gem5 and SystemC have evolved extensively and independent in parallel. Therefore, gem5 is incompatible to TLM models that exist in industry and academia.

In this paper, we present for the first time a comprehensive coupling between SystemC and gem5 that provides full interoperability. Through this coupling, any SystemC module that implements the TLM base protocol can be connected to any gem5 module, as shown in Figure 1. To the best of our knowledge, there exists no reference which describes syntax and semantics of both frameworks and how both simulation kernels can be coupled in order to enable full interoperability,



Paper: Link [1]

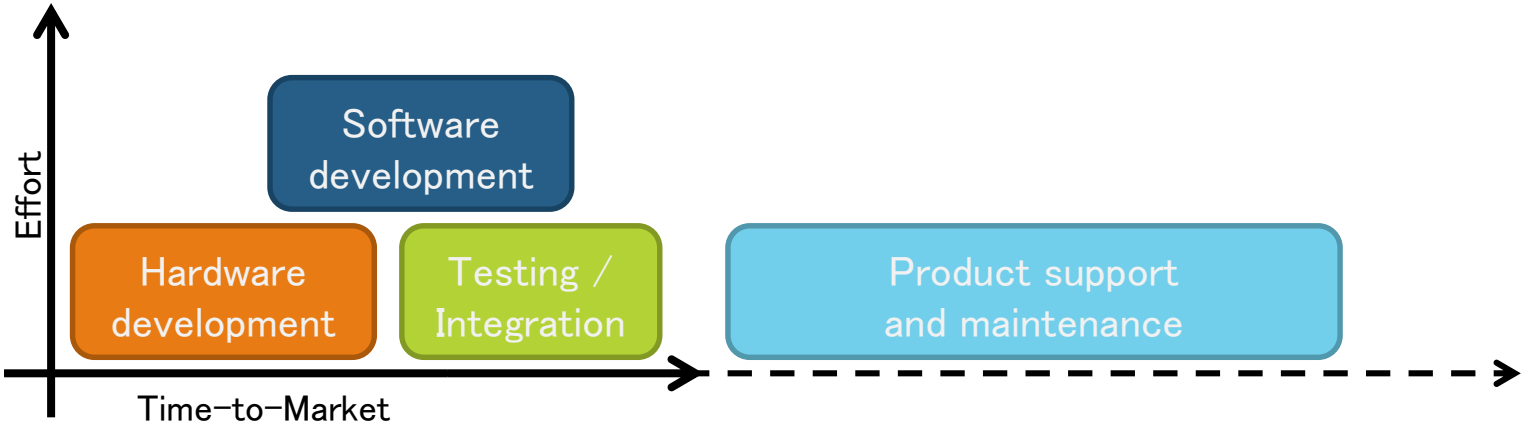
Sources: /gem5/utils/tlm/README

Virtual Prototyping

Virtual Prototypes in Industry

Functional software models of physical hardware:

- Visibility and controllability over the entire system
- Powerful debugging and analysis tools
- Reuse of components for future projects
- Fast Design Space Exploration (for HW engineers)
- Easy to exchange, worldwide
- Concurrent HW and SW development:



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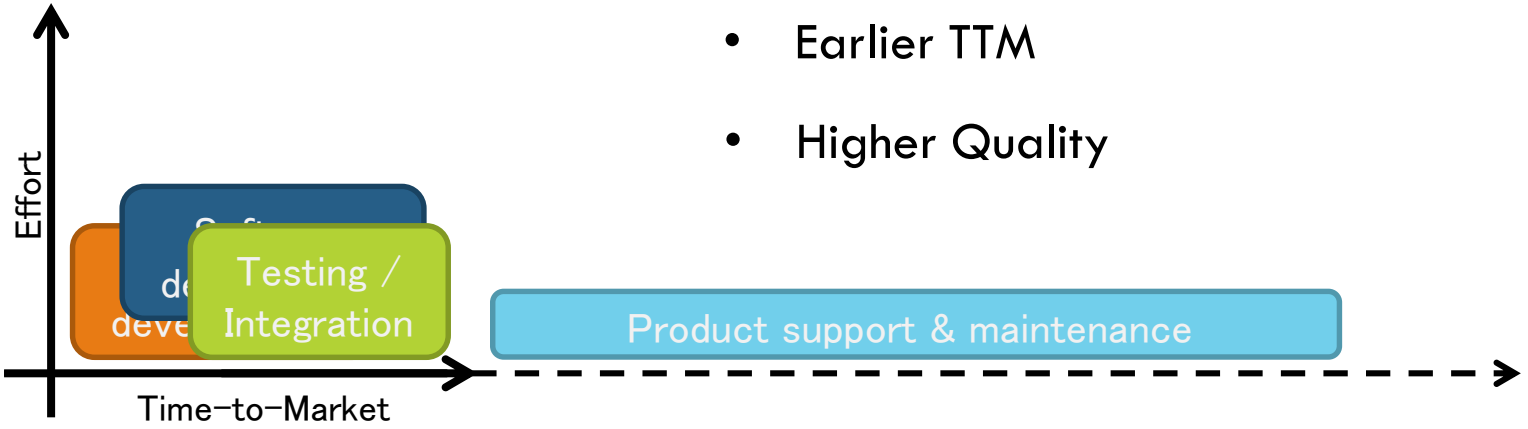
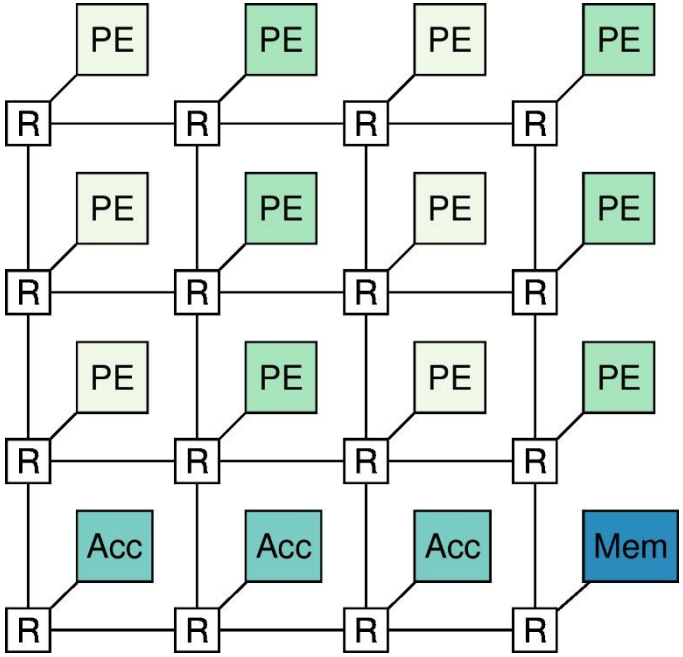


- Earlier TTM
- Higher Quality

Research Use Cases

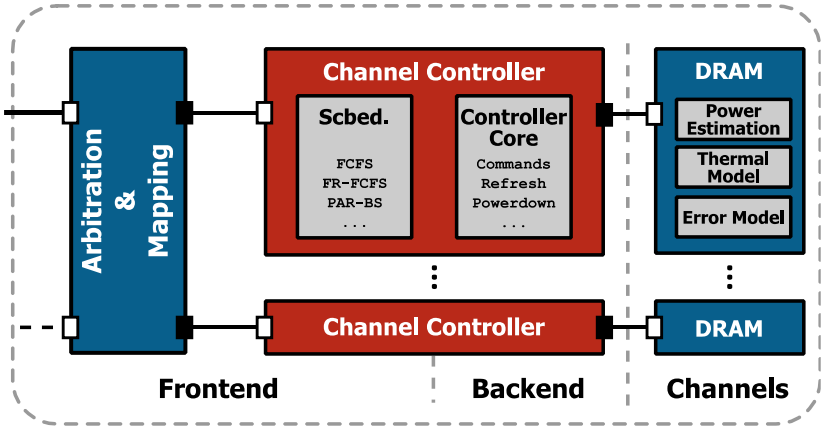
Simulation of (widely) heterogeneous systems



- Many different models of cores, accelerators, and communication infrastructure required.

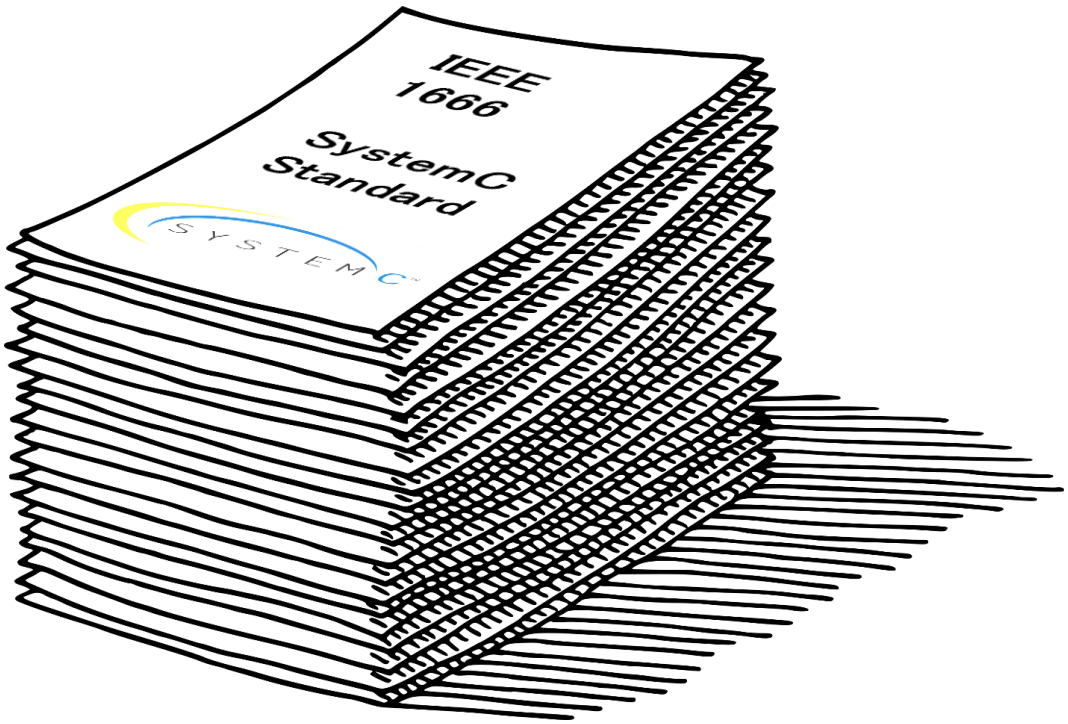
Simulation of the Memory Subsystem

DRAMSys



- Focuses on the memory subsystem, but detailed simulation of realistic workloads is required

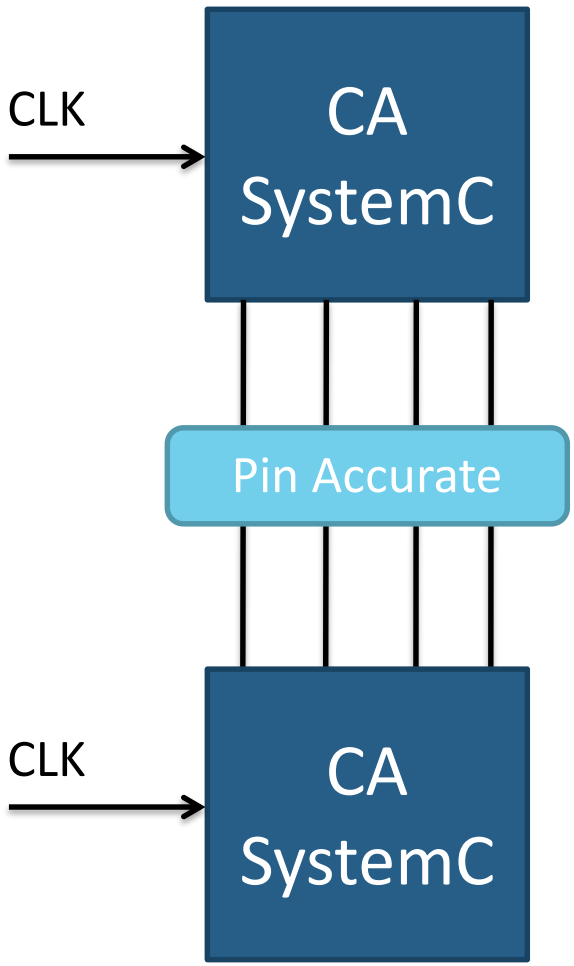
SystemC IEEE 1666



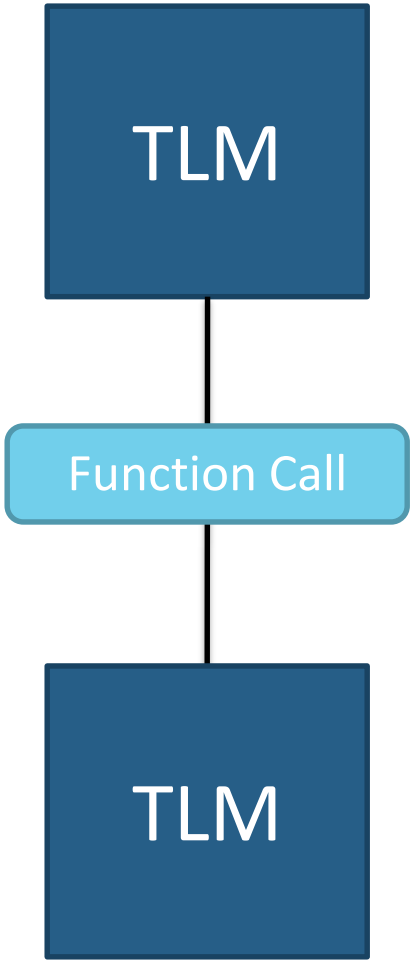
- Modeling language for HW and SW components
- Extends C++ to an event-driven simulation kernel
- Various levels of accuracy
- IEEE Standard, Maintained by Accellera
- 10-100x Faster than CA VHDL/Verilog Simulation

→ However, normal CA SystemC is not fast enough to, e.g., boot an OS.

Transaction Level Modeling (TLM)



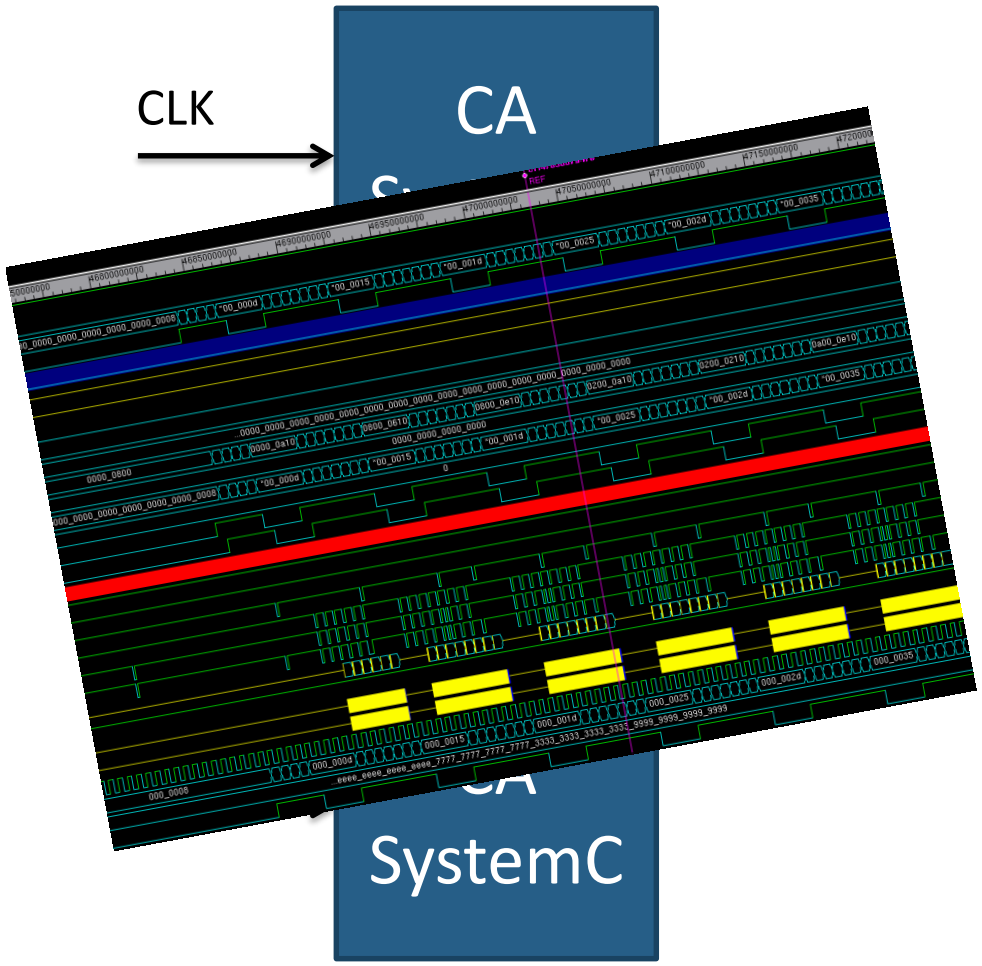
Simulate each pin separately



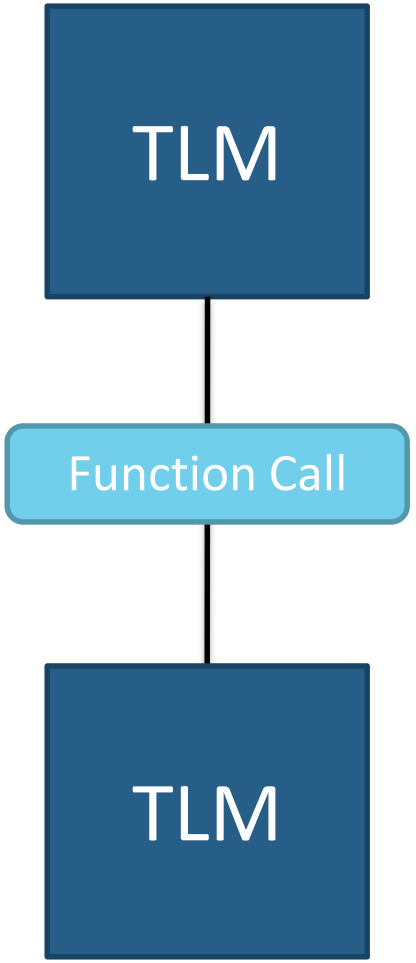
Simulate transactions up to 10,000x Faster

Source: Doulos Ldt. www.doulos.com

Transaction Level Modeling (TLM)



Simulate each pin separately



Simulate transactions up to 10,000x Faster

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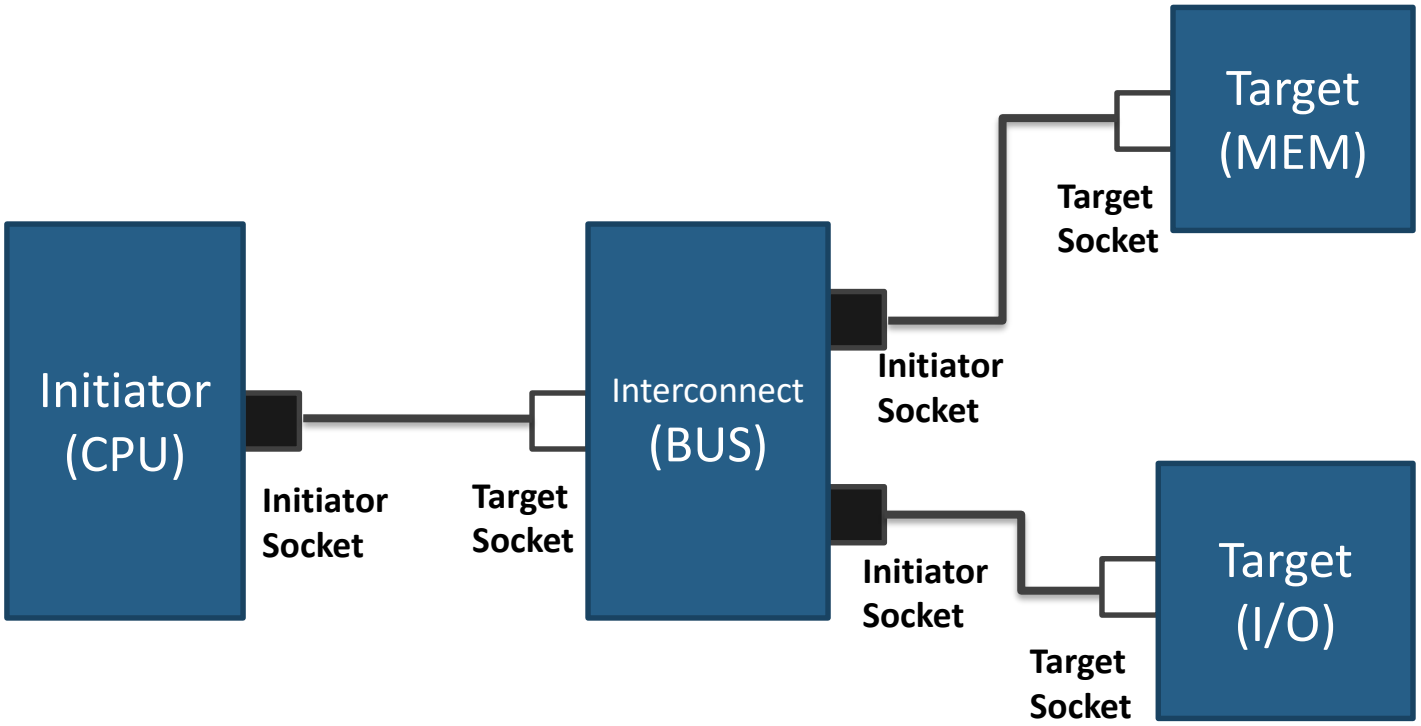
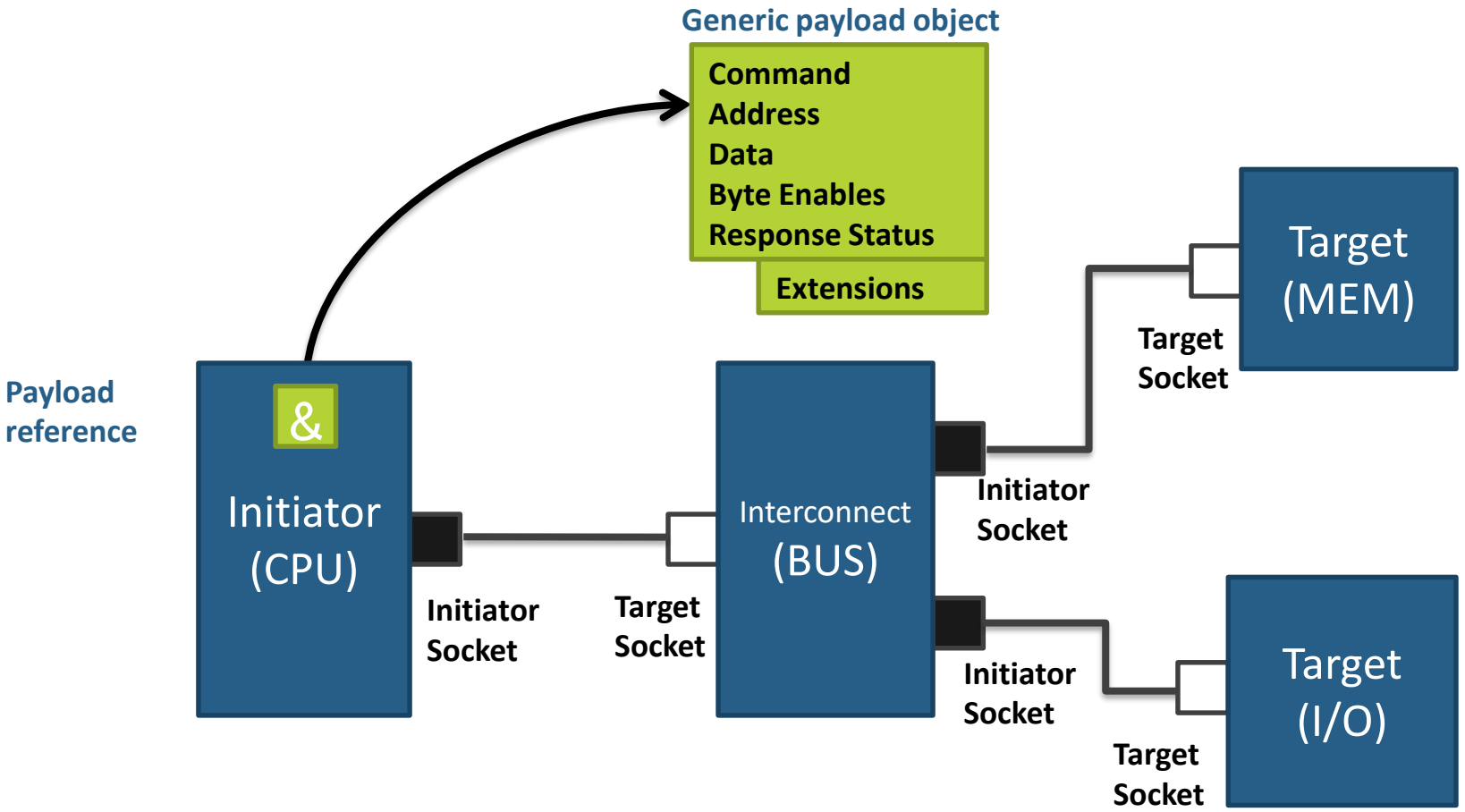
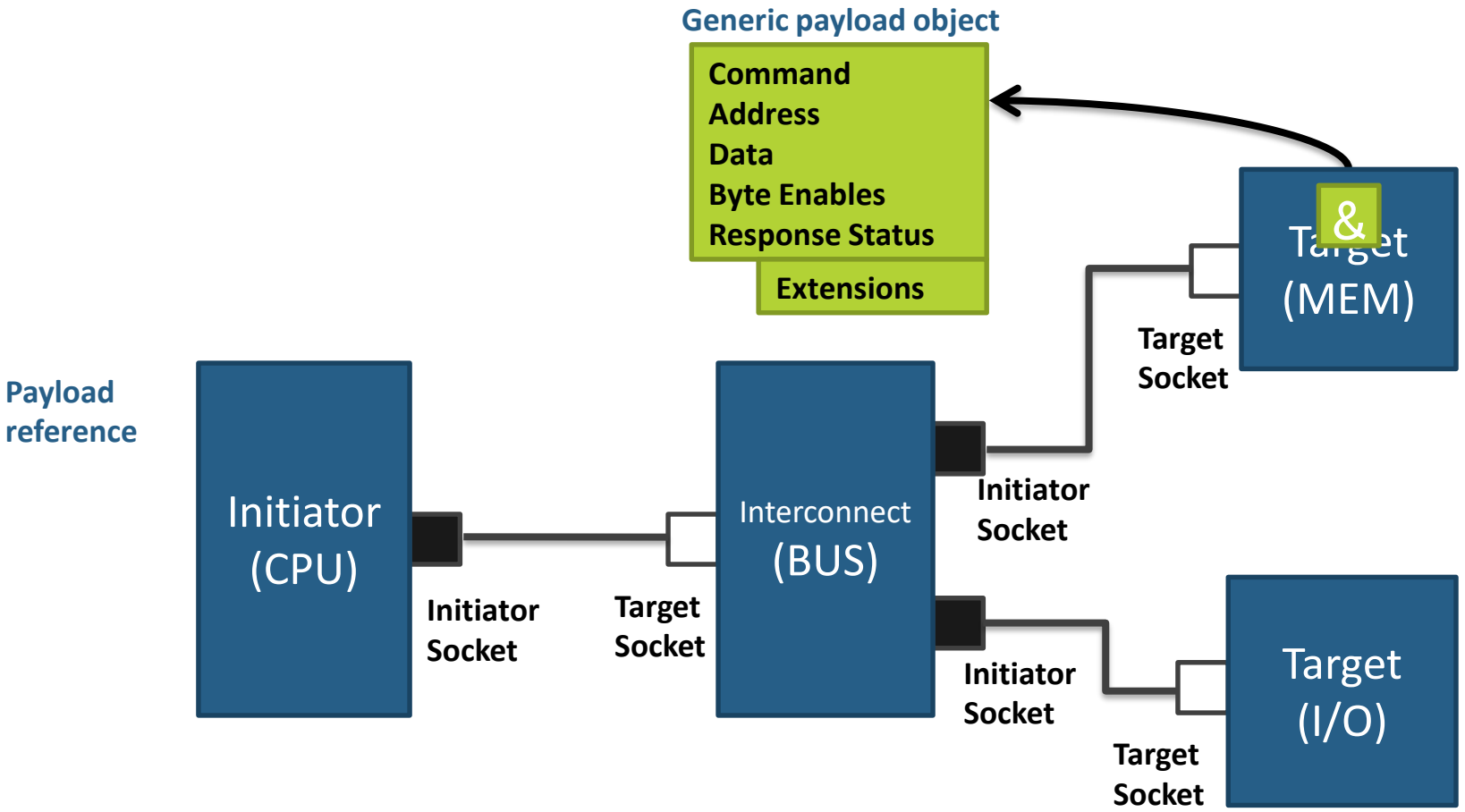
Generic Payload



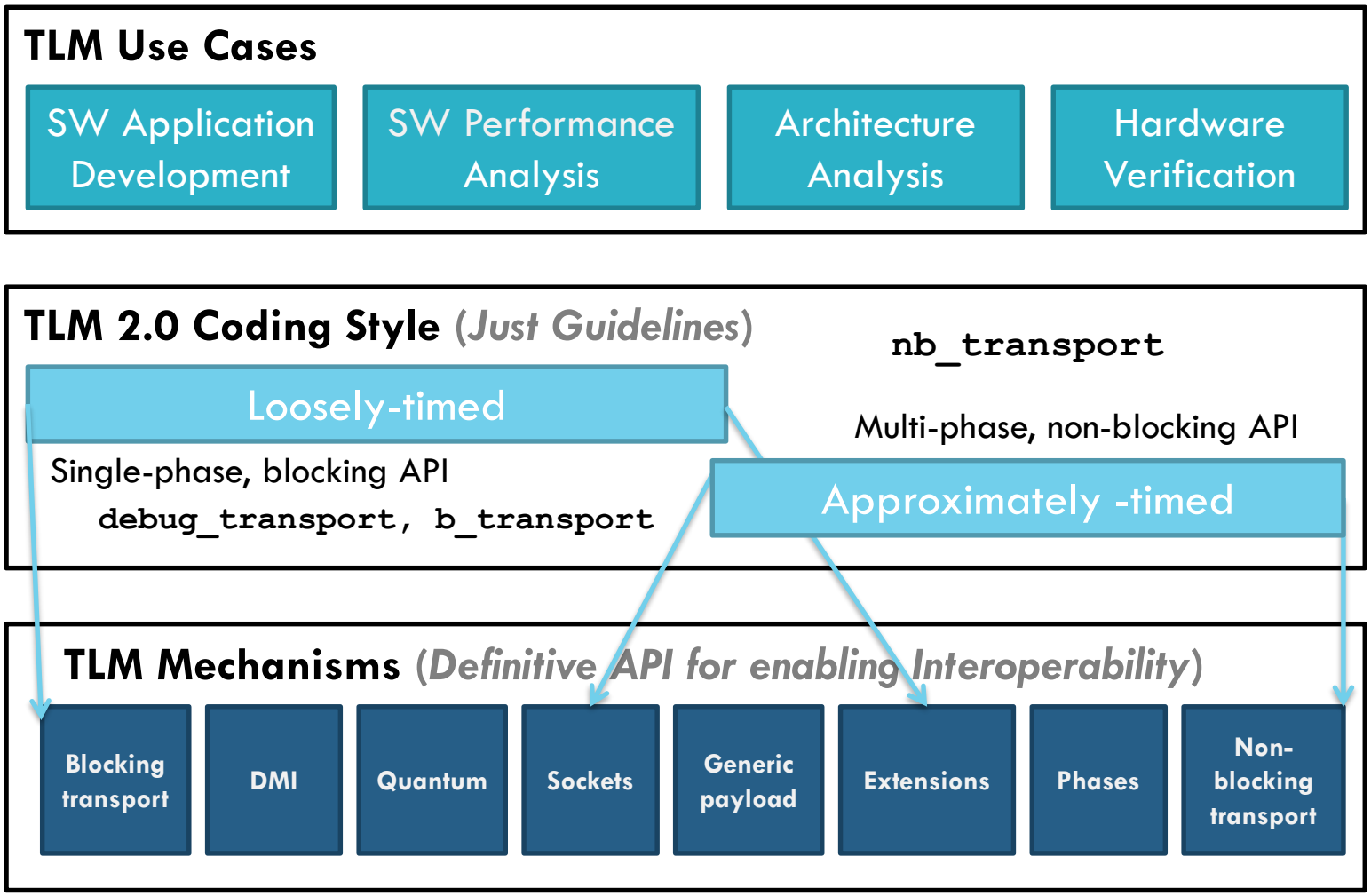
Generic Payload



Generic Payload



TLM Coding Styles and Mechanisms



Source: Doulos Ldt. www.doulos.com

Tool Vendors for TLM 2.0 VP

TLM is widely used in Industry:

- The market of virtual platform tools:
  - Synopsys - Platform Architect
  - Cadence - Virtual System Platform
  - Mentor Graphics - Vista Virtual prototyping
  - Imperas - OpenVP
  - ASTC - VLAB Works

- Virtual Platform Core Models:
  - ARM (Fastmodels):
    - only LT models based on JIT, non-free, library
  - ARM Carbon (Former Carbon Design Systems):
    - Cycle Accurate (CA) Models in TLM Wrapper, non-free, library
  - Imperas / OVP:
    - only LT, Free

→ An accurate, free available and changeable core model is needed

Coupling gem5 with SystemC

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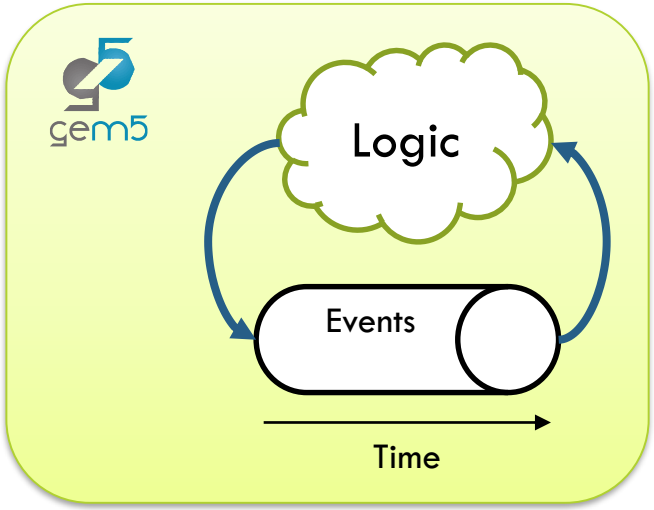
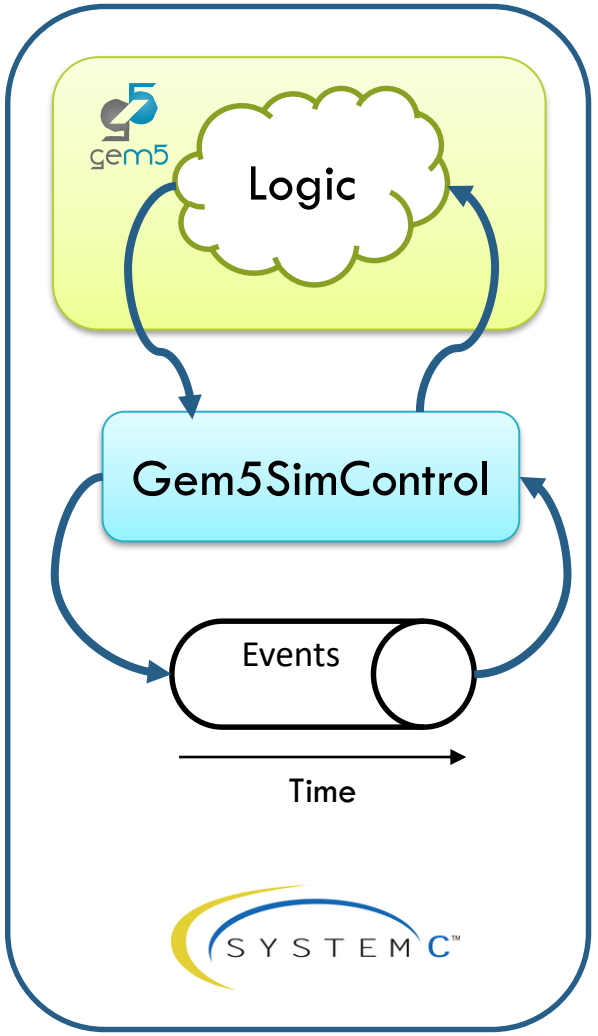
cfaed CENTER FOR ADVANCING ELECTRONICS DRESDEN
TECHNISCHE UNIVERSITÄT DRESDEN
MICROELECTRONIC SYSTEMS DESIGN RESEARCH GROUP
TECHNISCHE UNIVERSITÄT KAISERSLAUTERN
LEISTUNGSZENTRUM SIMULATIONS- UND SOFTWARE-BASIERTE INNOVATION
Fraunhofer IESE

Coupling gem5 with SystemC

gem5 supports a SystemC coupling:

- Gem5 is build as a C++ library.
- It is linked into a SystemC simulation.
- A SystemC object implements the gem5 event queue.
- **How can we communicate with other SystemC modules?**





Transaction Models in gem5

Timing

- The most detailed access: queuing delay + resource contention
- Similar to the TLM `nb_transport` interface.

Atomic

- Accesses are a faster than detailed access
- Used for **fast forwarding** and **warming up caches**
- Similar to the TLM `b_transport` interface
- Not good for performance simulation

Functional

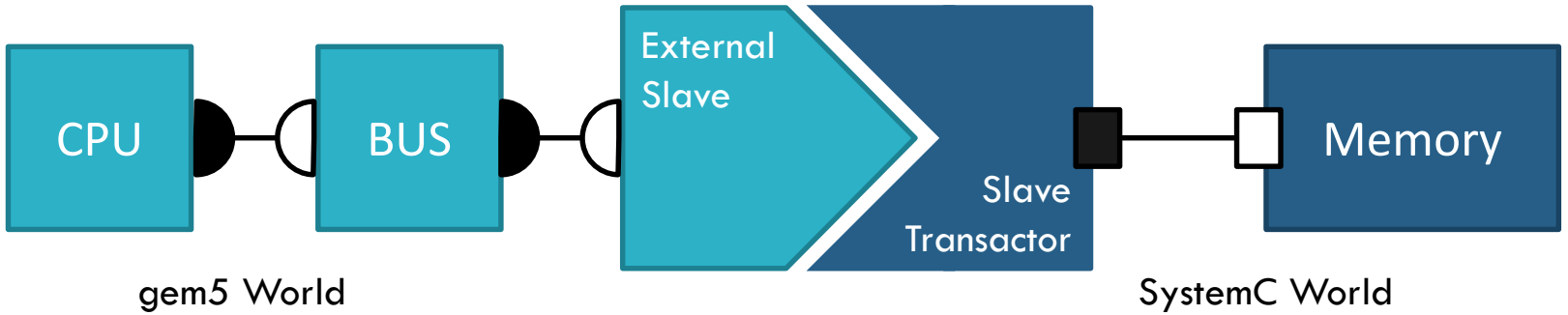
- Similar to `transport_dbg` e.g. loading binaries, avoiding deadlocks in multi-level cache coherent networks

Converting between TLM and gem5

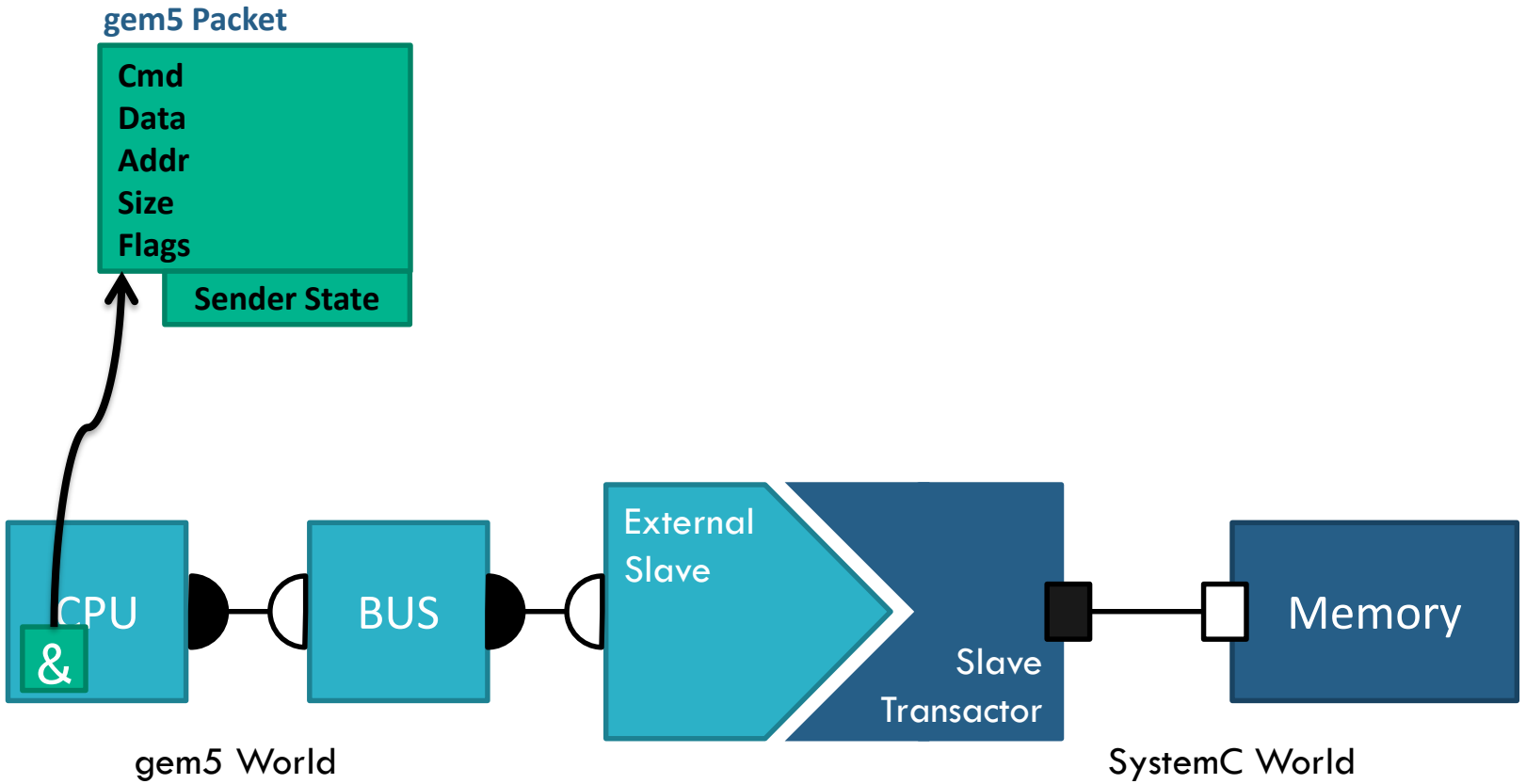

```
recvFunctional(…) → transport_dbg(…)
recvAtomic(…)     → b_transport(…)
recvTimingReq(…)  → nb_transport(…)
```


```
transport_dbg(…) → recvFunctional(…)
b_transport(…)   → recvAtomic(…)
nb_transport(…)  → recvTimingReq(…)
```

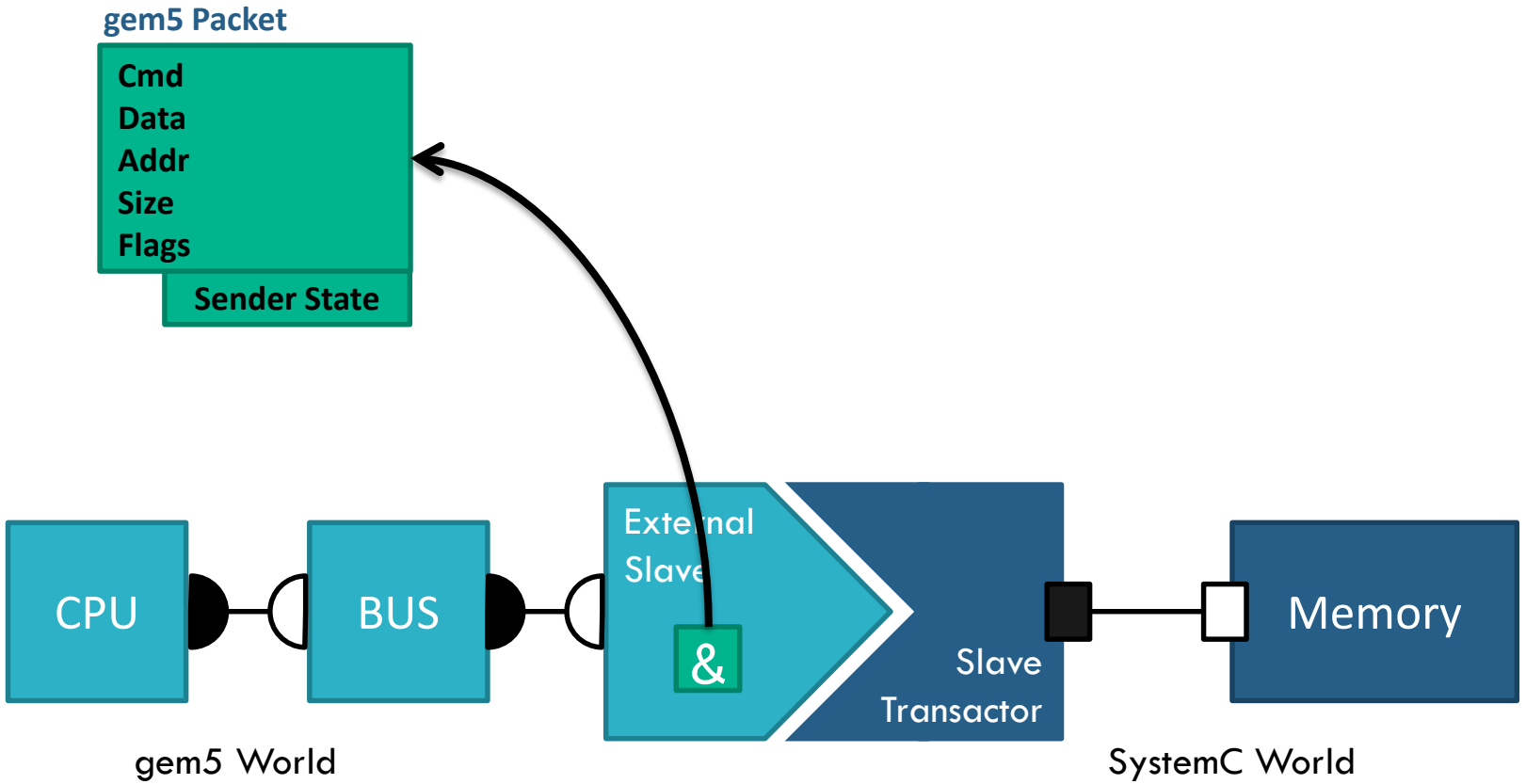
Transaction Explained



Transaction Explained



Transaction Explained



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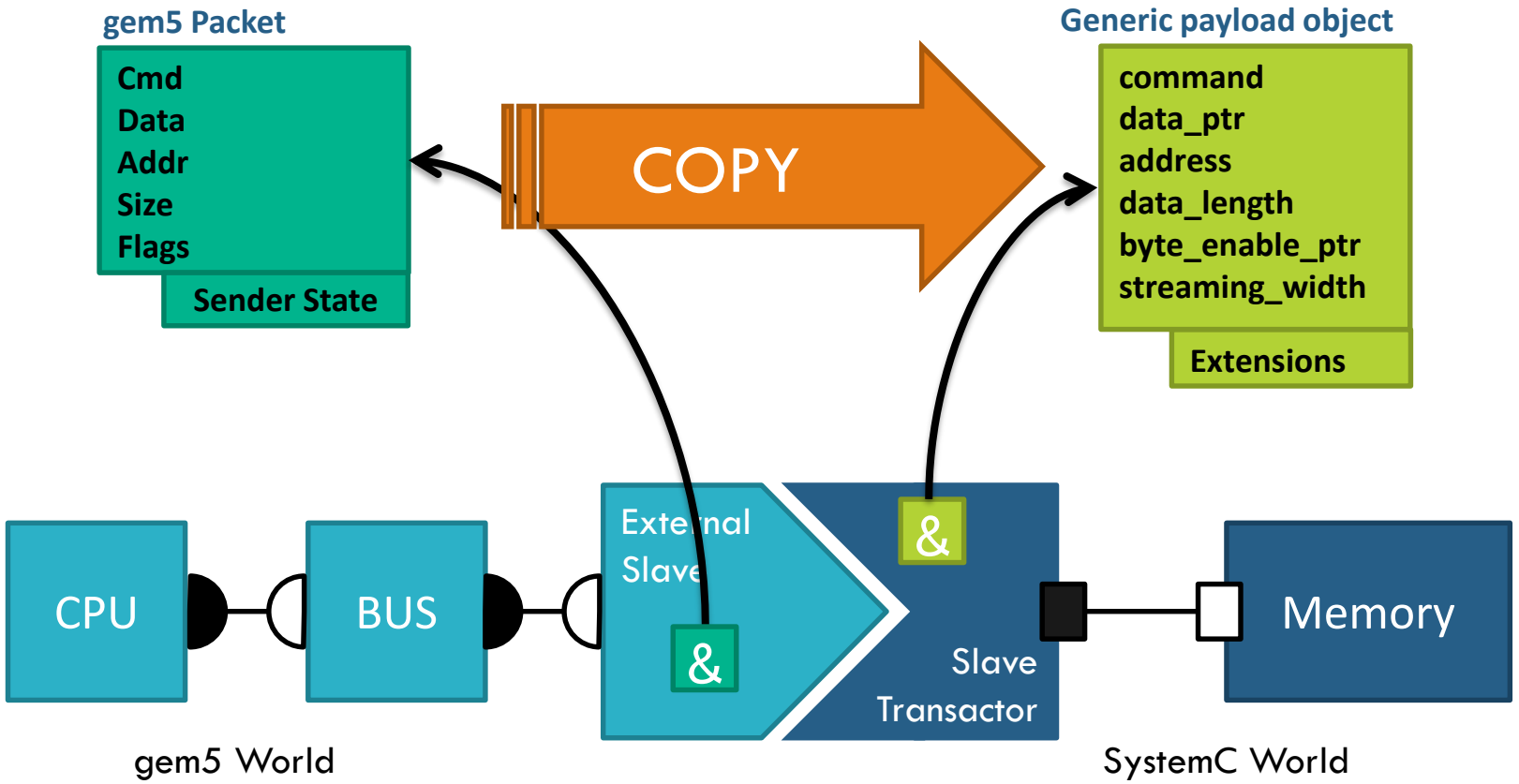
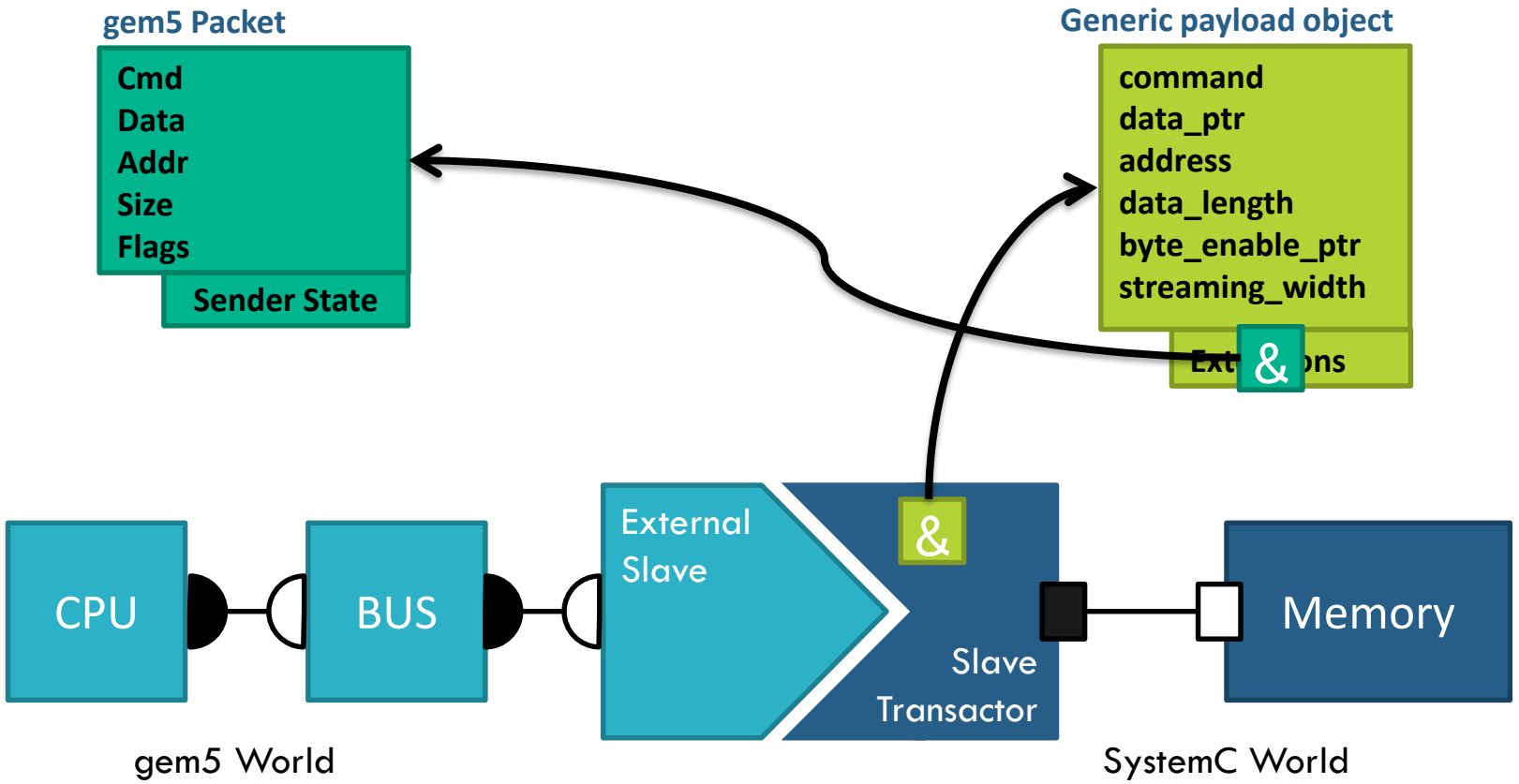


Transaction Explained



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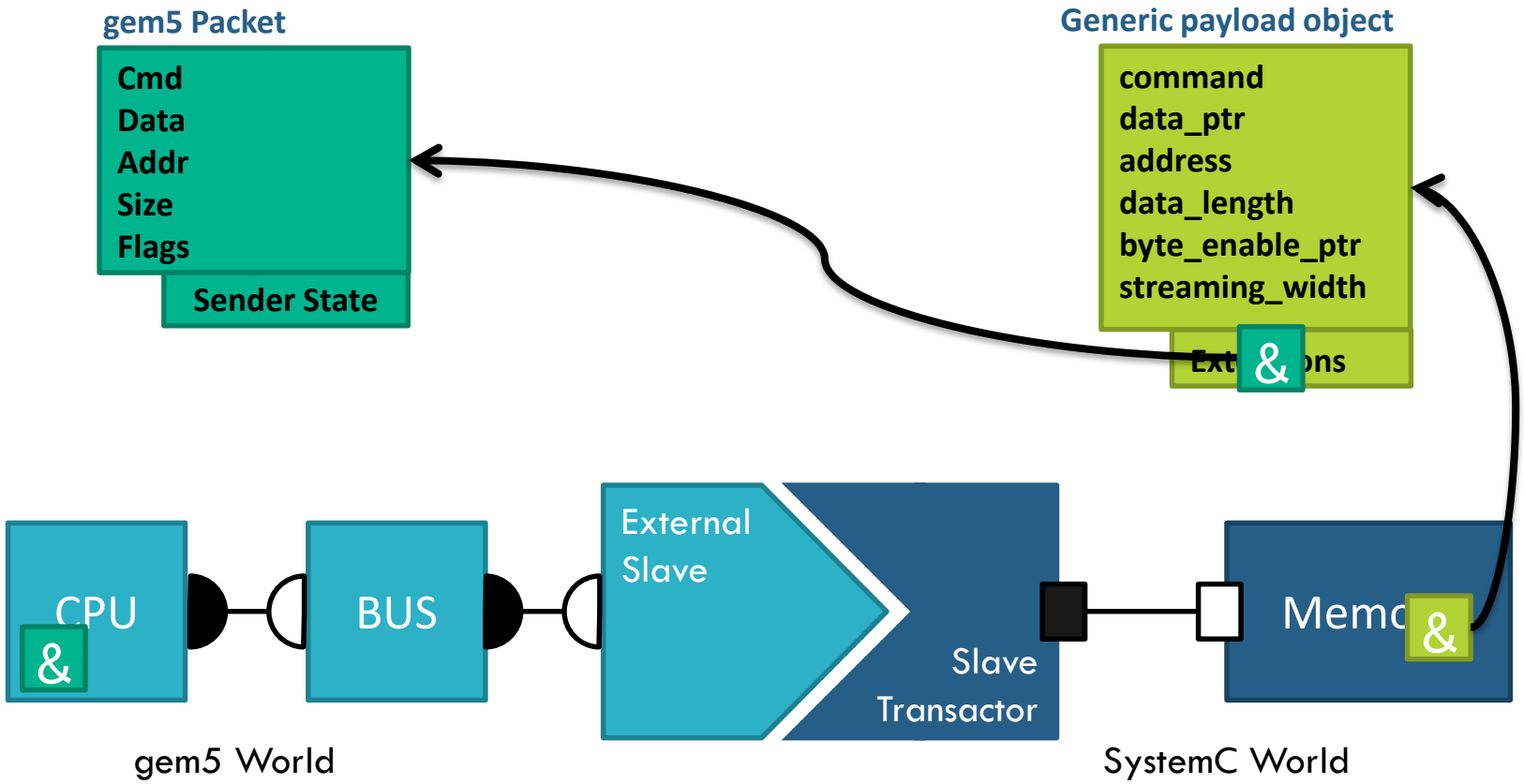
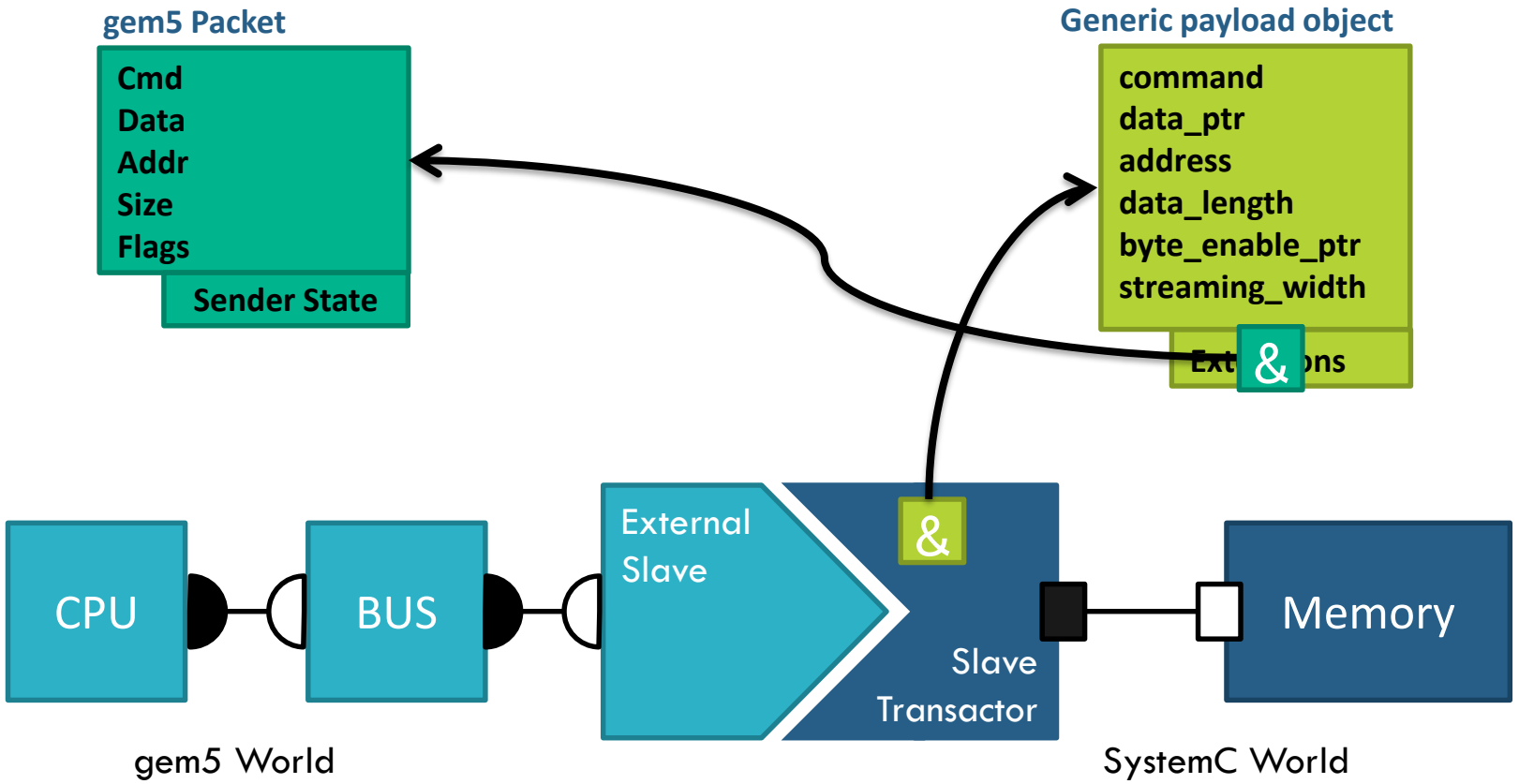
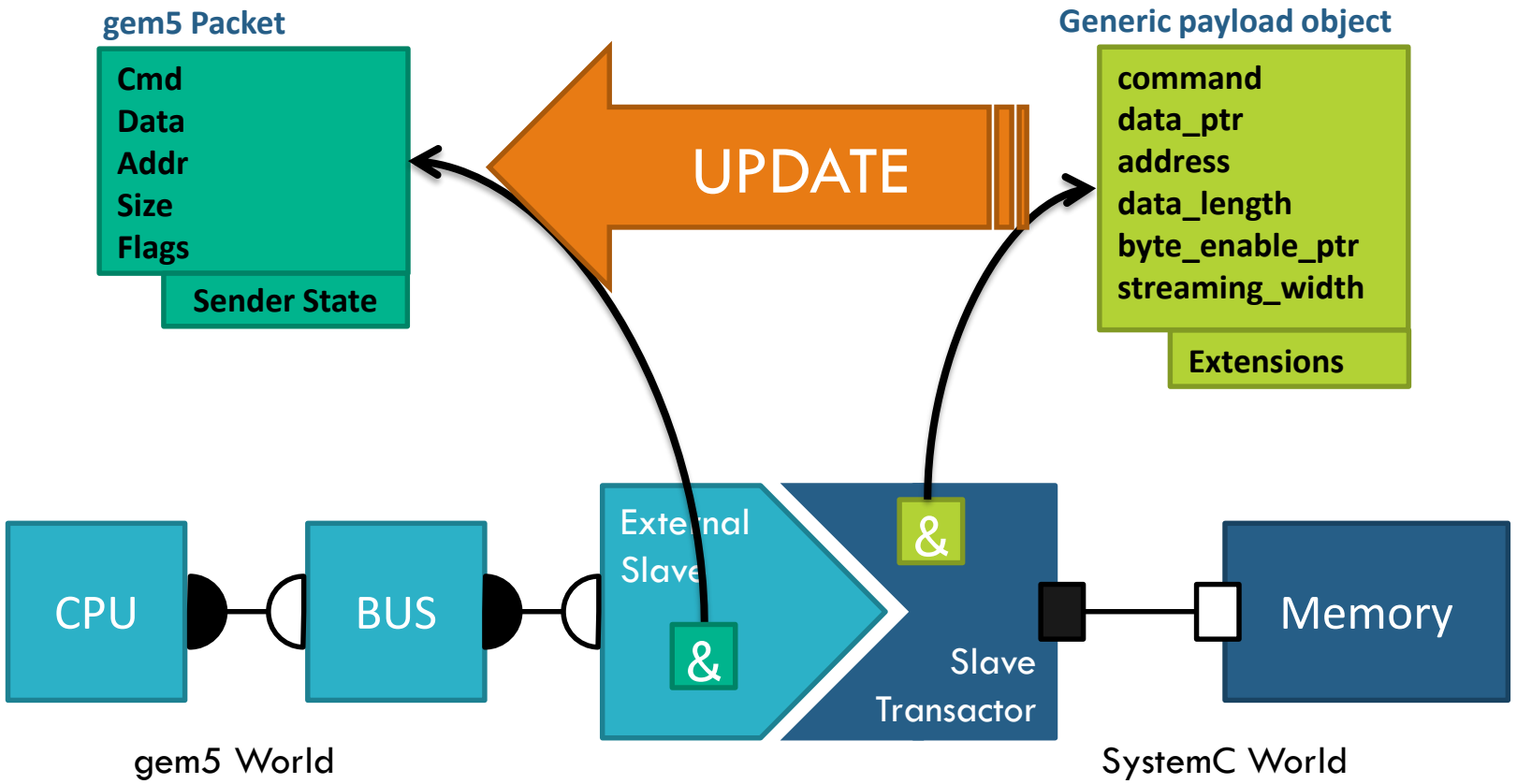


Transaction Explained



Transaction Explained



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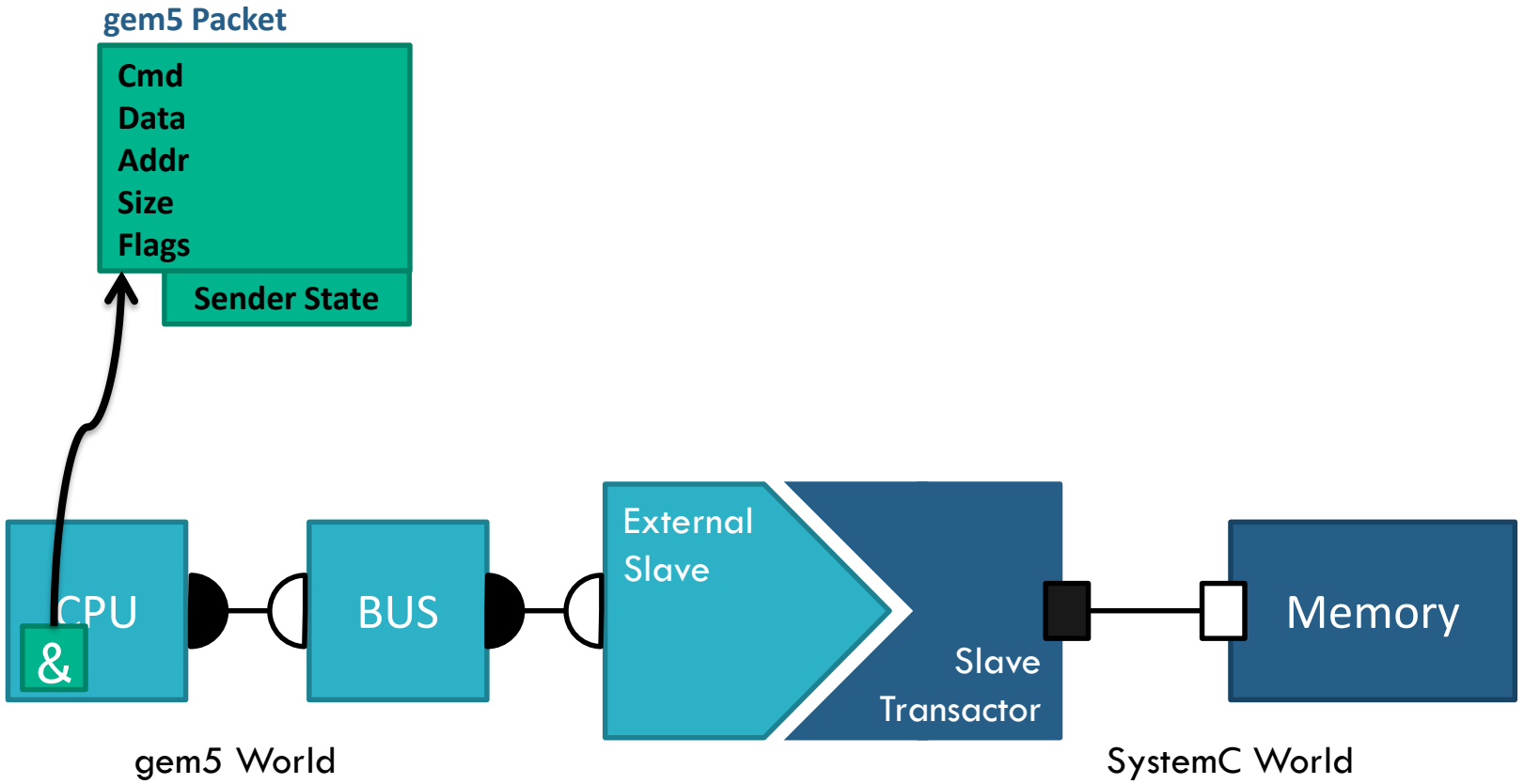
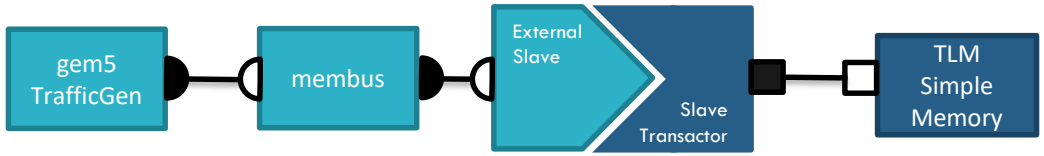


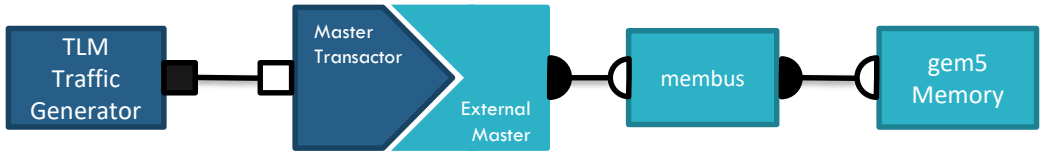
How to get Started?

How to get Started?

- Study the Examples in /gem5/utils/tlm/
  - Slave Example:

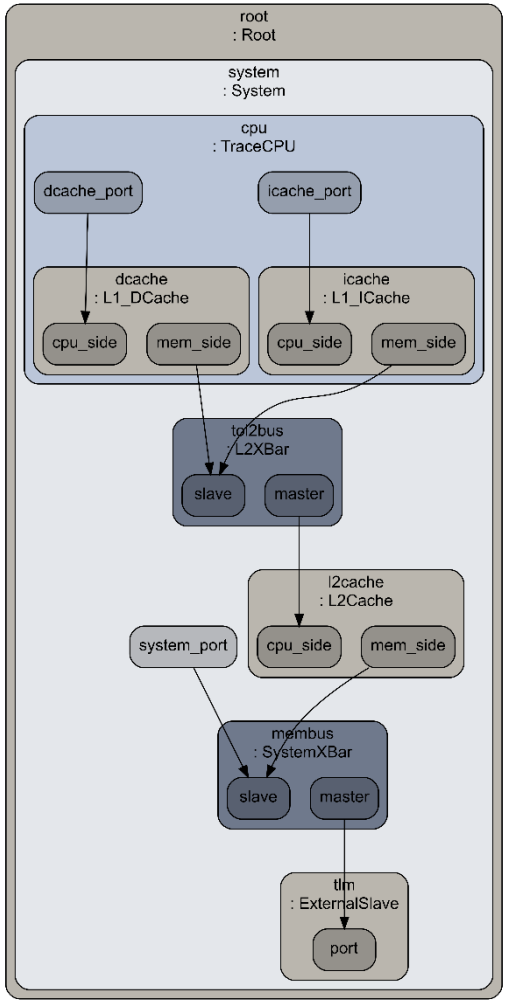


  - Master Example:



  - Elastic Trace Example [5] (see left)
  - Full System Example:

```
../../build/ARM/gem5.opt ../../configs/example/fs.py                \
--tlm-memory=transactor --cpu-type=TimingSimpleCPU --num-cpu=1      \
--mem-type=SimpleMemory --mem-size=512MB --mem-channels=1 --caches \
--l2cache --machine-type=VExpress_EMM                               \
--dtb-filename=vexpress.aarch32.ll_20131205.0-gem5.1cpu.dtb          \
--kernel=vmlinux.aarch32.ll_20131205.0-gem5                         \
--disk-image=linux-aarch32-ael.img
```



Practical Usage: General Flow

1. Compile gem5 normally: `scons build/ARM/gem5.opt`
2. Compile gem5 as a library:

```
scons --with-cxx-config --without-python --without-tcmalloc \
      build/ARM/libgem5_opt.so
```

3. Include the gem5 modules `Gem5SimControl` and `Gem5SlaveTransactor` and/or `Gem5MasterTransactor` in your SystemC project and connect them to your SystemC models. Be sure to pass an individual port name to the constructor of each transactor.
4. Compile your project and link against the gem5 library.
5. Run normal gem5 with a custom python script or fs.py with `--tlm-memory=<port-name>` to generate `m5out/config.ini`. Be sure to set the `tlm_data` attribute of the External Masters/Slaves to the port name of the corresponding SystemC transactor.
6. Run your SystemC project and pass the `m5out/config.ini` file to your `Gem5SimControl` object.

Hands On: A Memory Module in SystemC

```
struct Target: public sc_module {
  // TLM interface socket:
  tlm_utils::simple_target_socket<Target> socket;

  // Storage
  unsigned char *mem;

  // Constructor
  Target(sc_core::sc_module_name name, /* ... */);
  SC_HAS_PROCESS(Target);

  // TLM interface functions
  virtual void b_transport(tlm::tlm_generic_payload& trans,
                                    sc_time& delay);
  virtual unsigned int transport_dbg(tlm::tlm_generic_payload& trans);
  virtual tlm::tlm_sync_enum nb_transport_fw(
                tlm::tlm_generic_payload& trans,
                tlm::tlm_phase& phase,
                sc_time& delay);

  // ...
};
```

➔ util/tlm/examples/slave_port/sc_target.hh

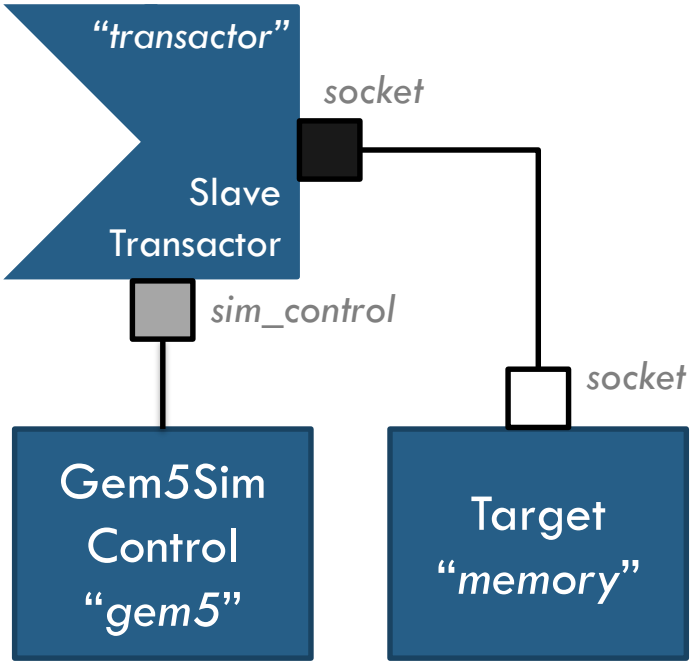
Hands On: Connect the Memory to gem5

```
int sc_main(int argc, char **argv)
{
    // Instantiate all modules
    Gem5SystemC::Gem5SimControl
            sim_control("gem5", /* config ... */);
    Gem5SystemC::Gem5SlaveTransactor
            transactor("transactor", "transactor");
    Target memory("memory", /* config ... */);

    // Bind modules
    memory.socket.bind(transactor.socket);
    transactor.sim_control.bind(sim_control);

    // Start simulation
    sc_core::sc_start();

    return EXIT_SUCCESS;
}
```



➔ util/tlm/examples/slave_port/main.cc

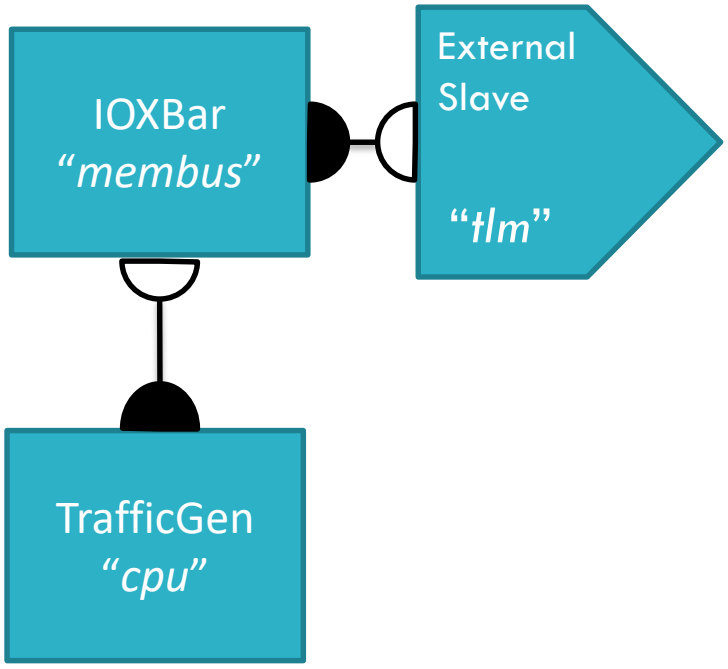
Hands On: Configure gem5

```
# Create a system with a Crossbar and a
TrafficGenerator
system = System()
system.membus = IOXBar(width = 16)
# This must be instanciated, even if not needed
system.physmem = SimpleMemory()
system.cpu = TrafficGen(config_file = "tgen.cfg")
system.clk_domain = SrcClockDomain(clock = '1.5GHz',
    voltage_domain = VoltageDomain(voltage = '1V'))

# Create an external TLM port:
system.tlm = ExternalSlave()
system.tlm.addr_ranges = [AddrRange('512MB')]
system.tlm.port_type = "tlm_slave"
system.tlm.port_data = "transactor"

# Route the connections:
system.cpu.port = system.membus.slave
system.system_port = system.membus.slave
system.membus.master = system.tlm.port

# Start the simulation:
root = Root(full_system = False, system = system)
root.system.mem_mode = 'timing'
m5.instantiate()
m5.simulate()
```



➔ util/tlm/conf/tlm_slave.py

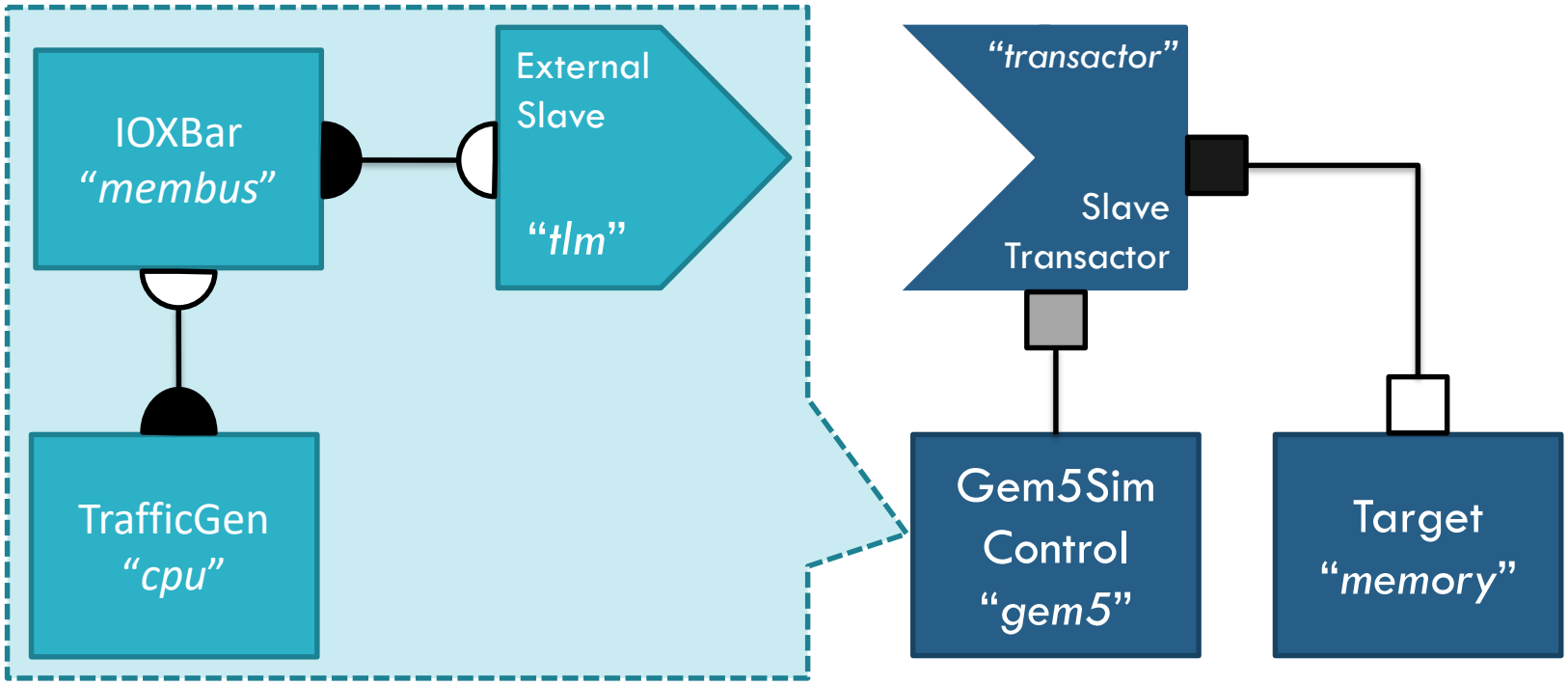
Hands On: Run the Simulation

1. Build the example: `$ cd util/tlm && scons`
2. Create a gem5 config.ini file:

```
$ ../../build/ARM/gem5.opt conf/tlm_slave.py
```

3. Run the simulation:

```
$ build/examples/slave_port/gem5.sc m5out/config.ini
```



Hands On: Simulation Output

```
$ build/examples/slave_port/gem5.sc m5out/config.ini -e 200000 -d TrafficGen
[…]
0 s (=) : sc_main Start of Simulation
info: Entering event queue @ 0.  Starting simulation...
5 ns (=) : system.cpu LinearGen::getNextPacket: r to addr 0, size 4
5 ns (=) : system.cpu Next event scheduled at 10000
10 ns (=) : system.cpu LinearGen::getNextPacket: w to addr 4, size 4
15 ns (=) : system.cpu Received retry
15 ns (=) : system.cpu LinearGen::getNextPacket: r to addr 8, size 4
16675 ps (=) : system.cpu Received retry
75 ns (=) : system.cpu Received retry
75 ns (=) : system.cpu LinearGen::getNextPacket: r to addr c, size 4
76038 ps (=) : system.cpu Received retry
135 ns (=) : system.cpu Received retry
135 ns (=) : system.cpu LinearGen::getNextPacket: r to addr 10, size 4
136068 ps (=) : system.cpu Received retry
195 ns (=) : system.cpu Received retry
195 ns (=) : system.cpu LinearGen::getNextPacket: w to addr 14, size 4
196098 ps (=) : system.cpu Received retry
Exit at tick 200000, cause: simulate() limit reached
```

➔ The binary excepts various options:

- -e end of simulation at tick
- -d set a gem5 debug flag

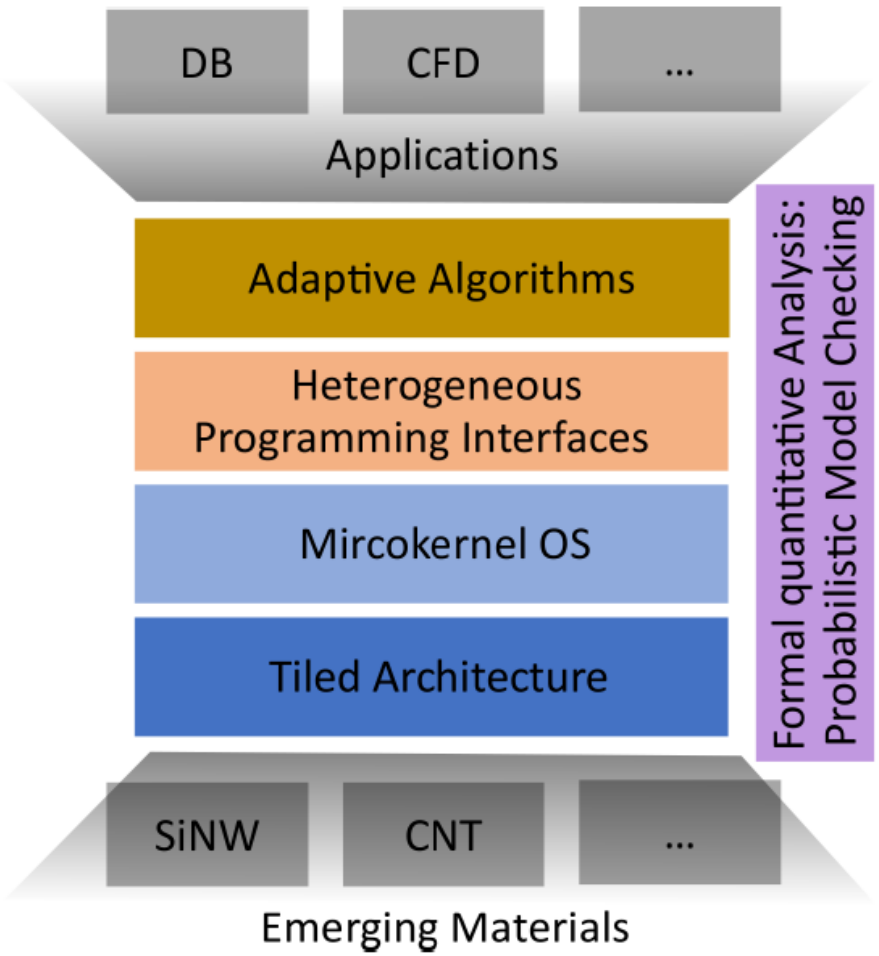
Usecases

The Orchestration Path at CFAED [2]

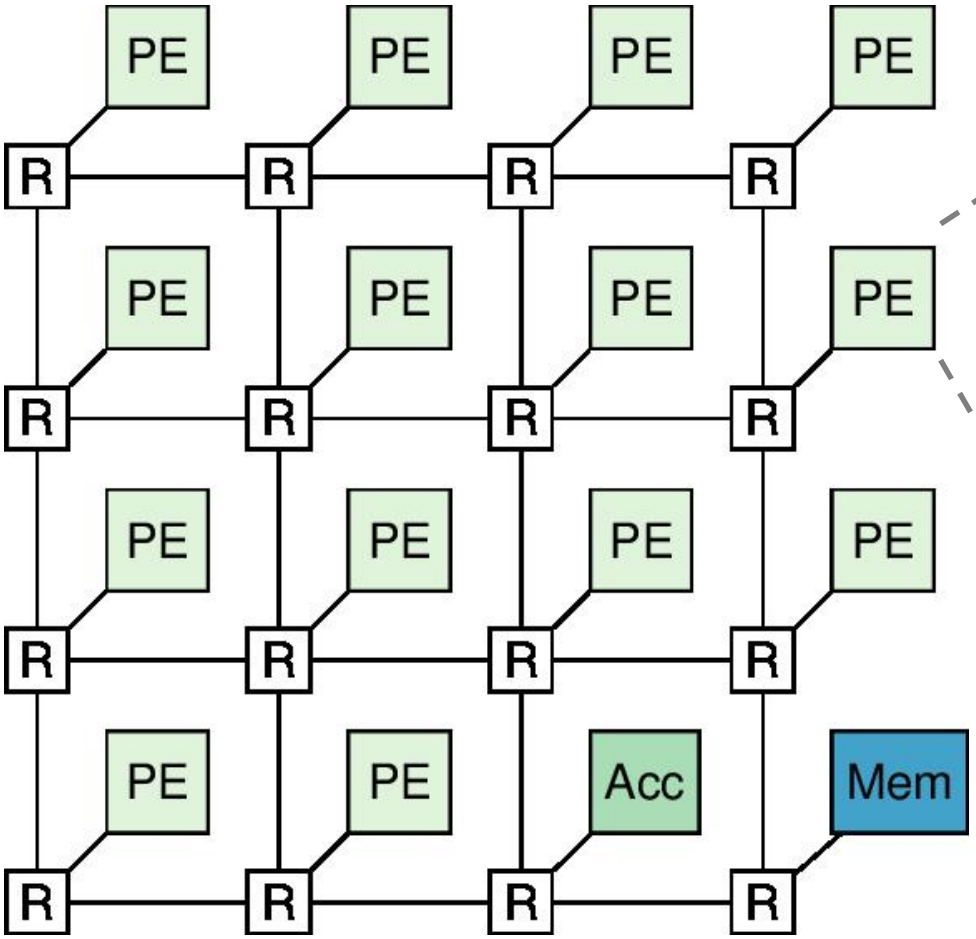
A programming stack for wildly heterogeneous systems including:

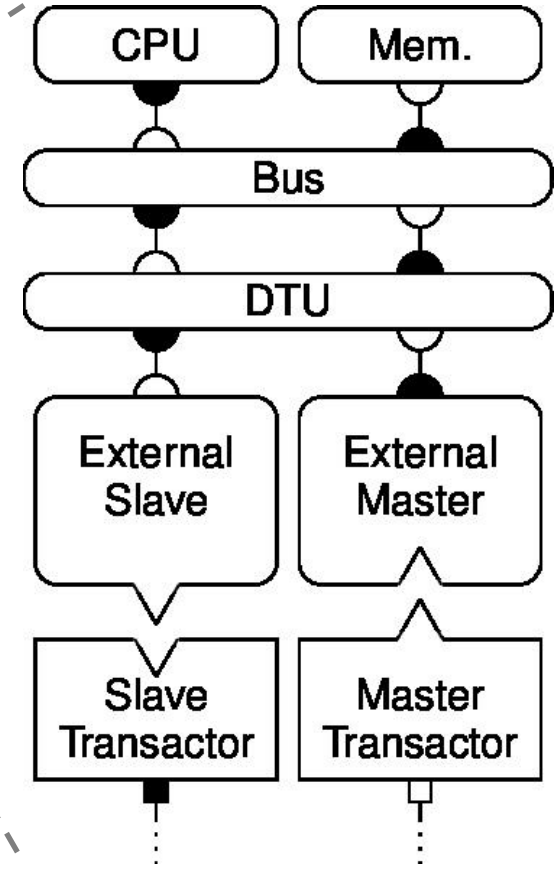
- dataflow programming models
- dataflow compiler
- adaptive runtime systems
- capability-based OS
- model checker

➔ A flexible simulation platform is required to try new designs and technologies.

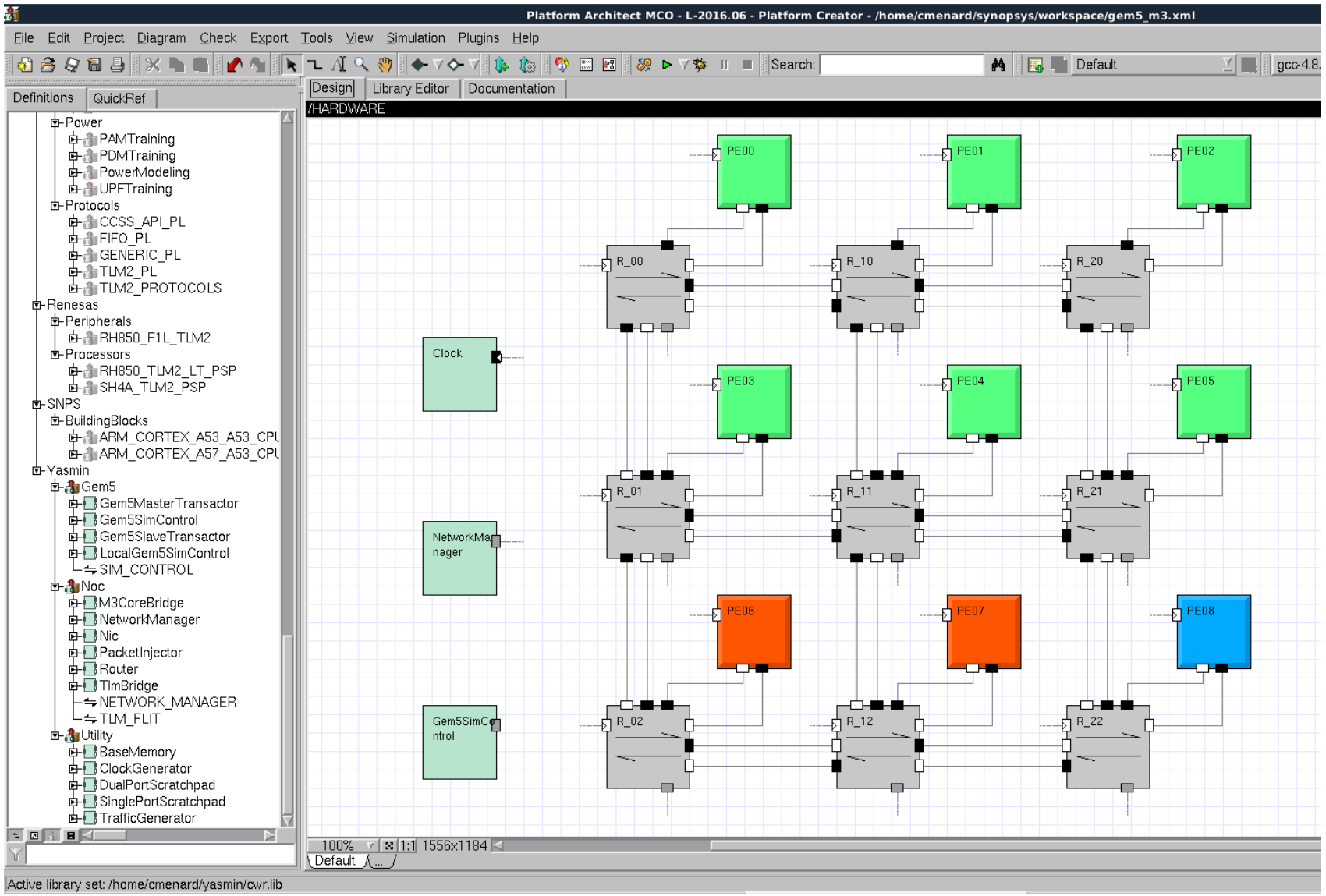


Building Heterogeneous MPSoCs: gem5 as a Tile

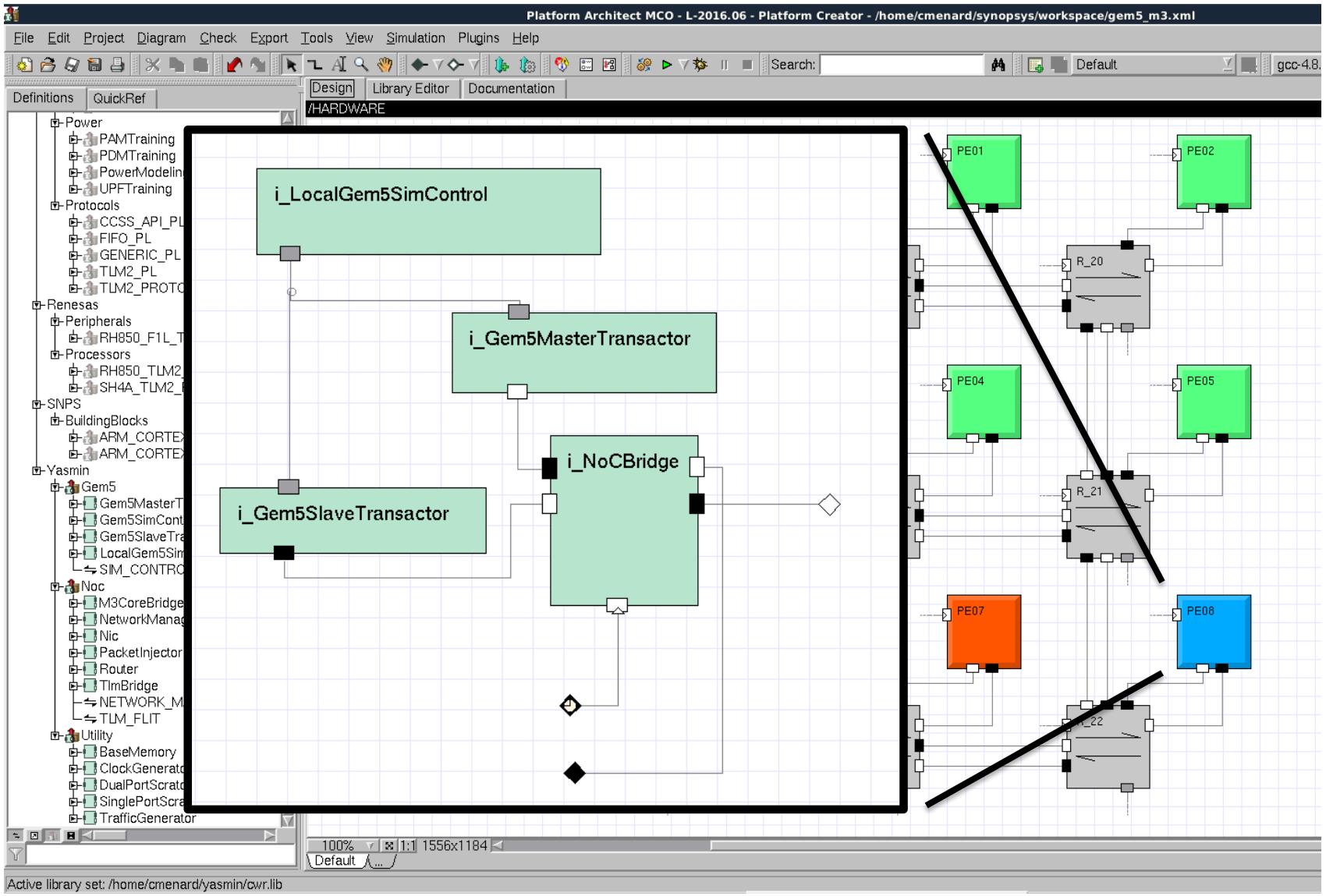




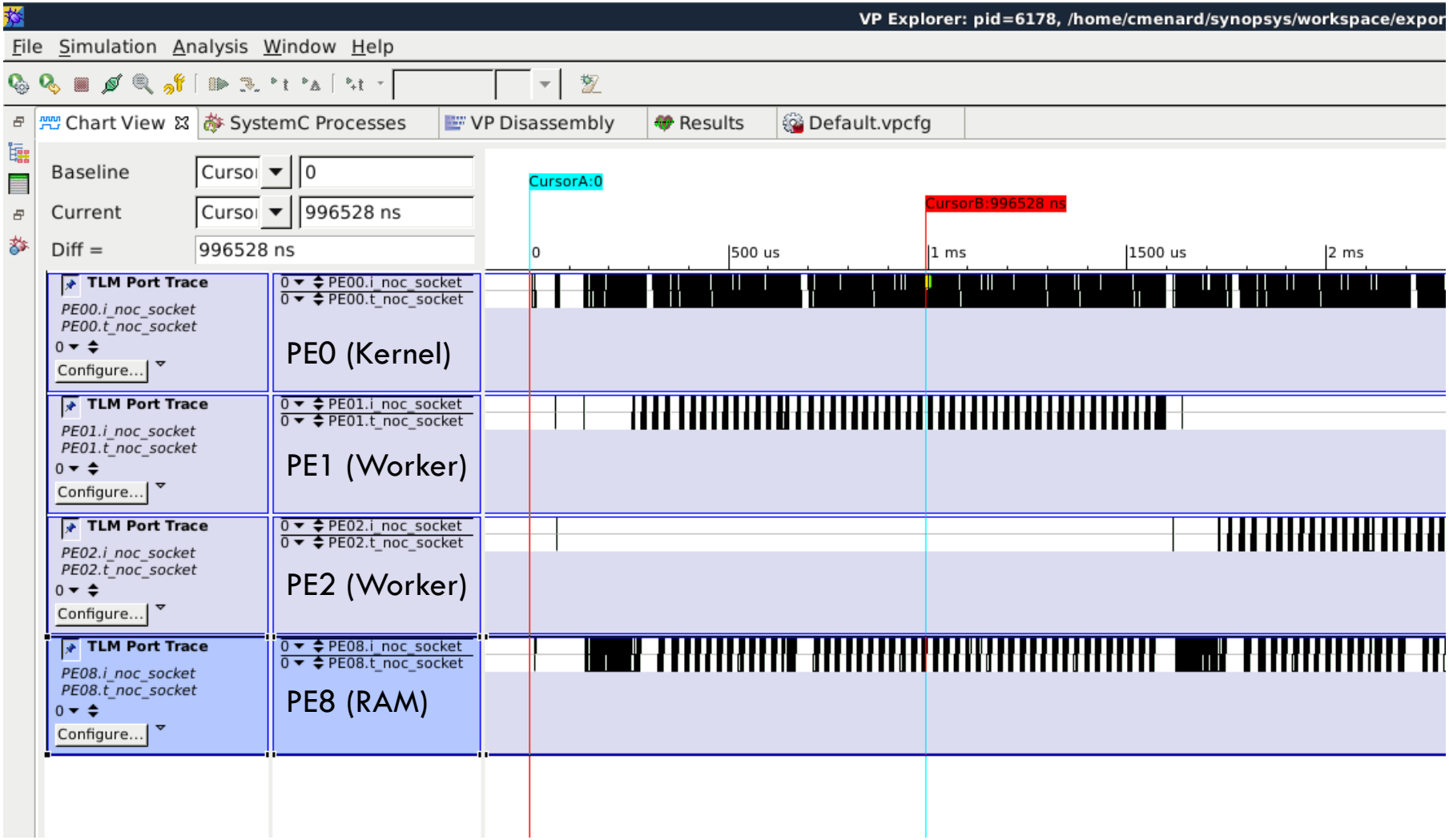
gem5 in Synopsys Platform Architect



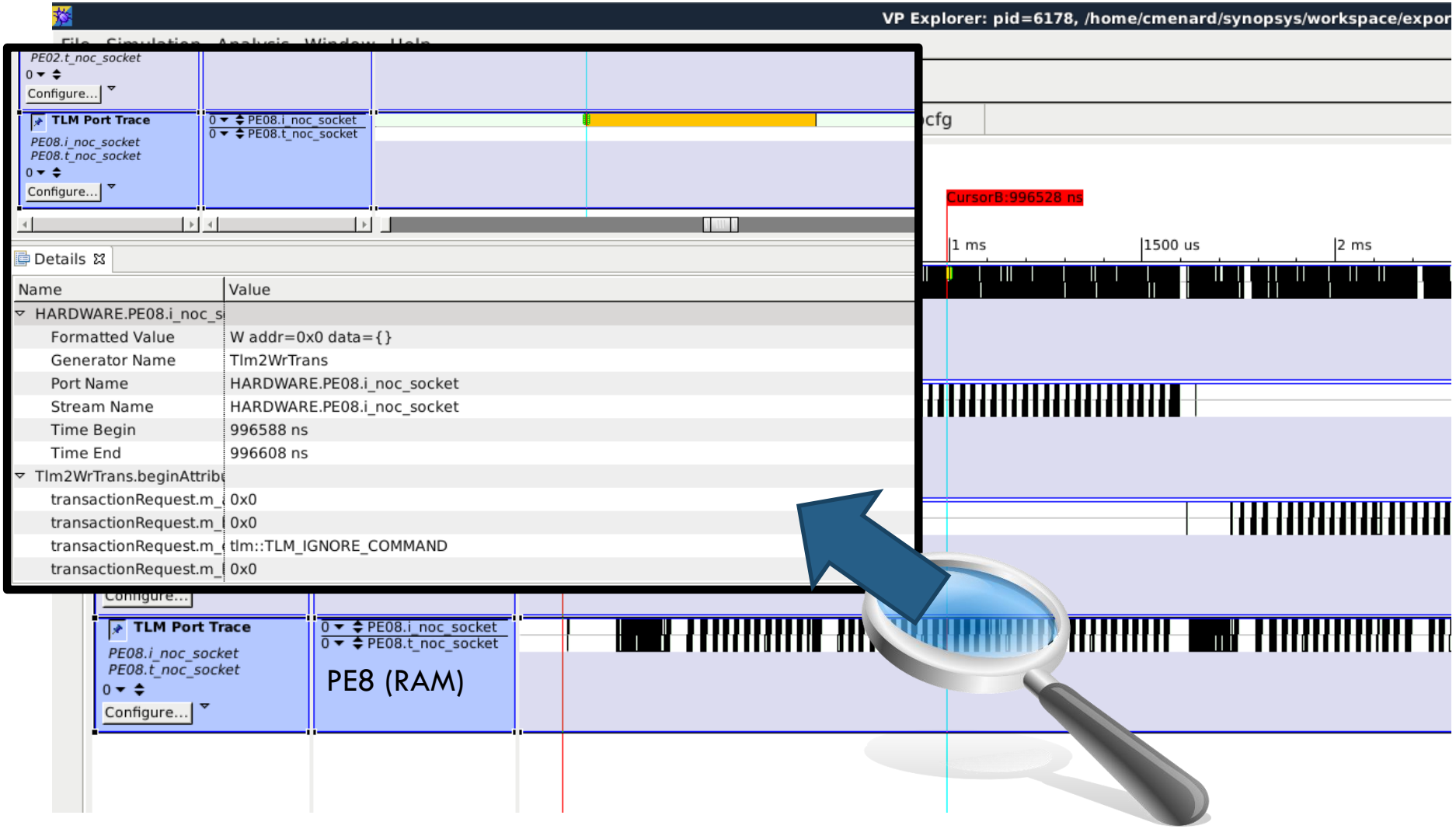
gem5 in Synopsys Platform Architect



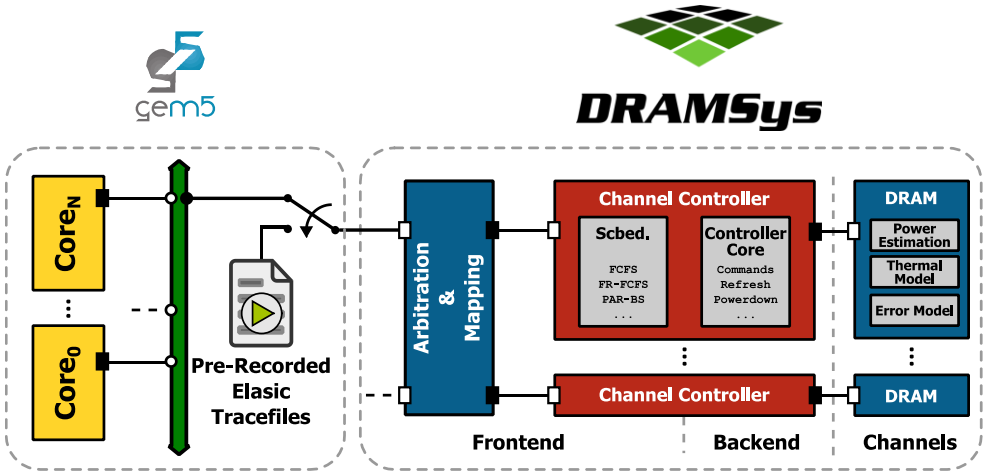
gem5 in Synopsys Platform Architect: Trace Analysis



gem5 in Synopsys Platform Architect: Trace Analysis

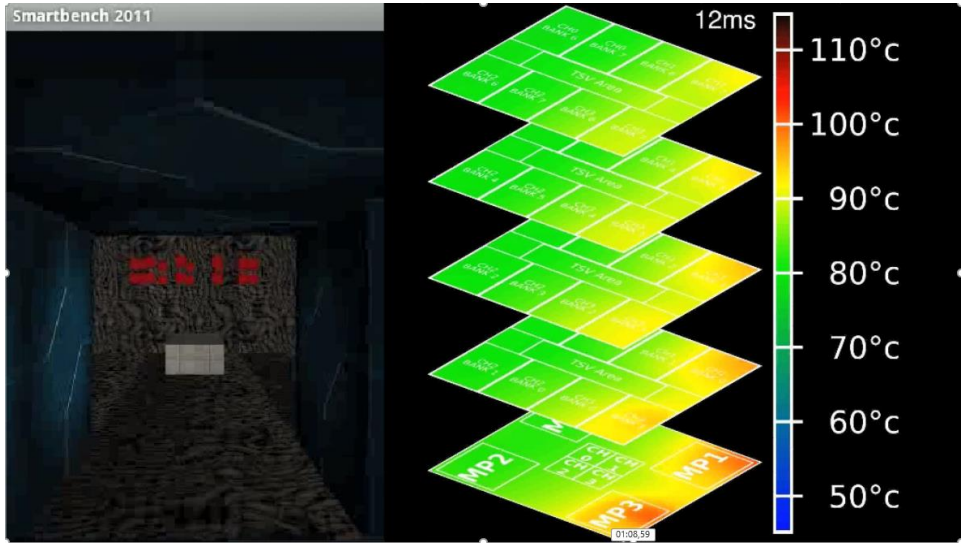


Coupling gem5 with DRAMSys [3], [4]



DRAMPower

3D



DRAMSys is a design space exploration framework for DRAM and memory controller

It includes:

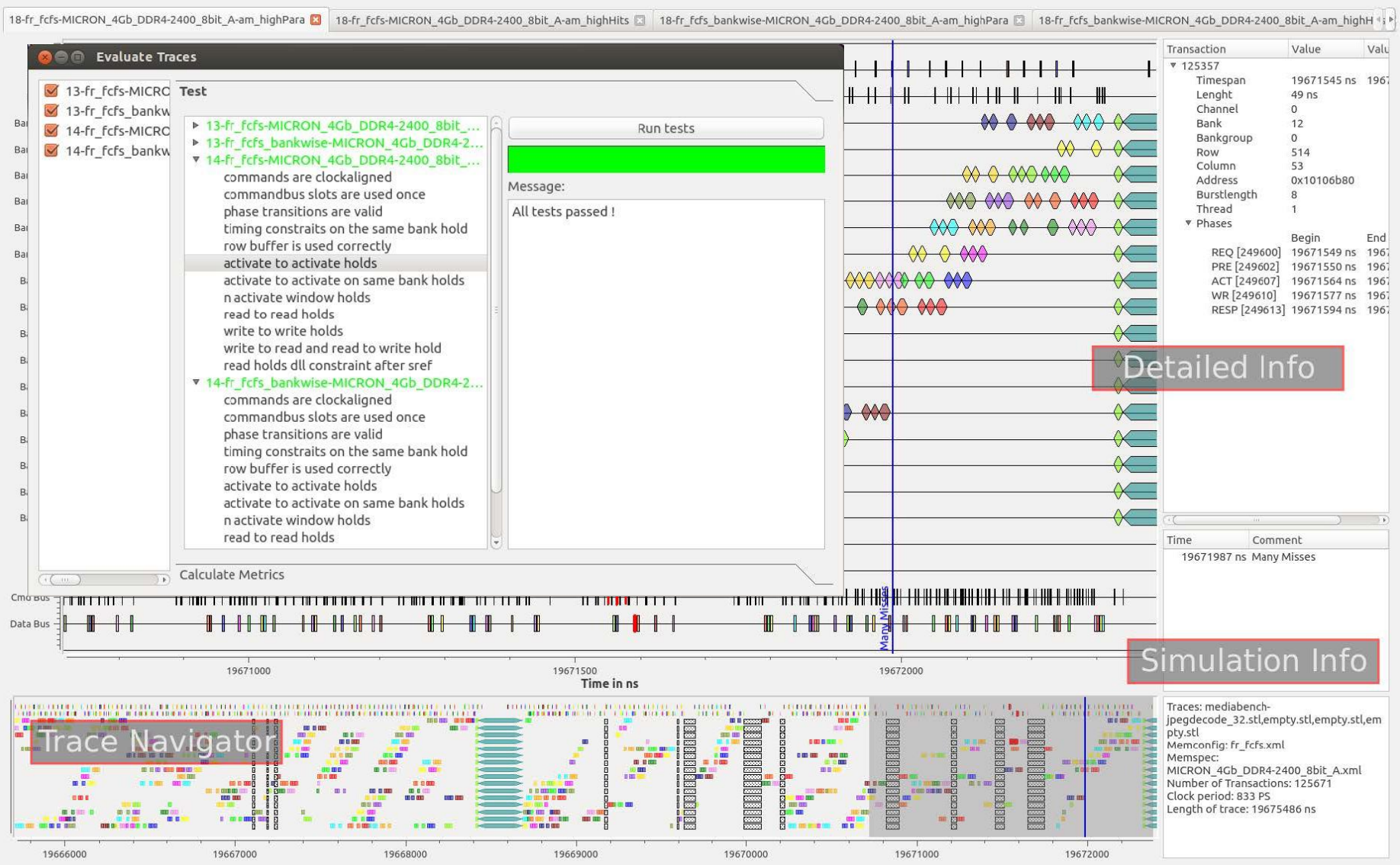
- Power model
- Thermal model
- Retention error model.

Linux boot (without thermal model) using the DRAMSys model → slowdown of 1.9×

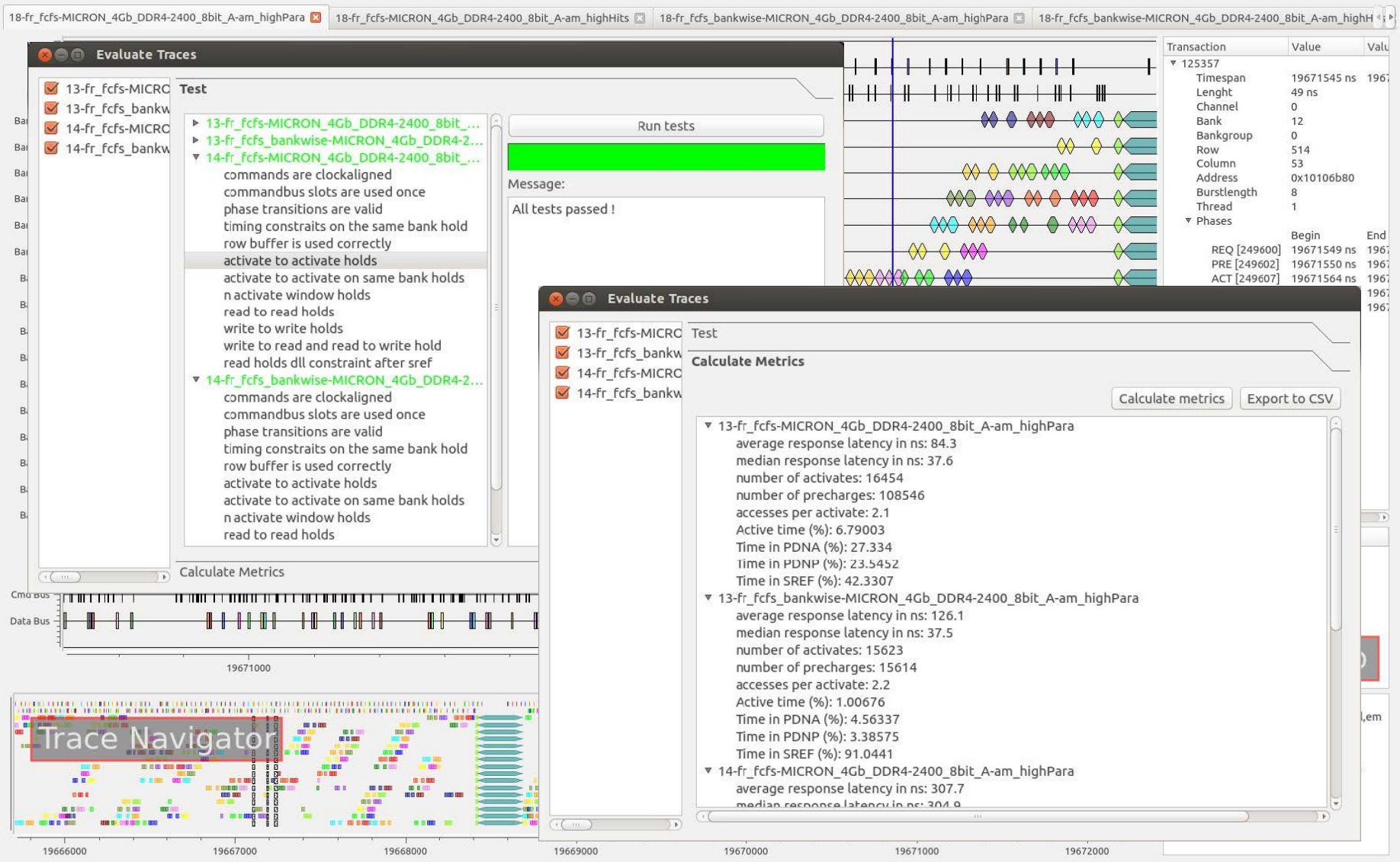
This slowdown mostly comes from detailed DRAMSys model

Coupling gem5 with DRAMSys Continued

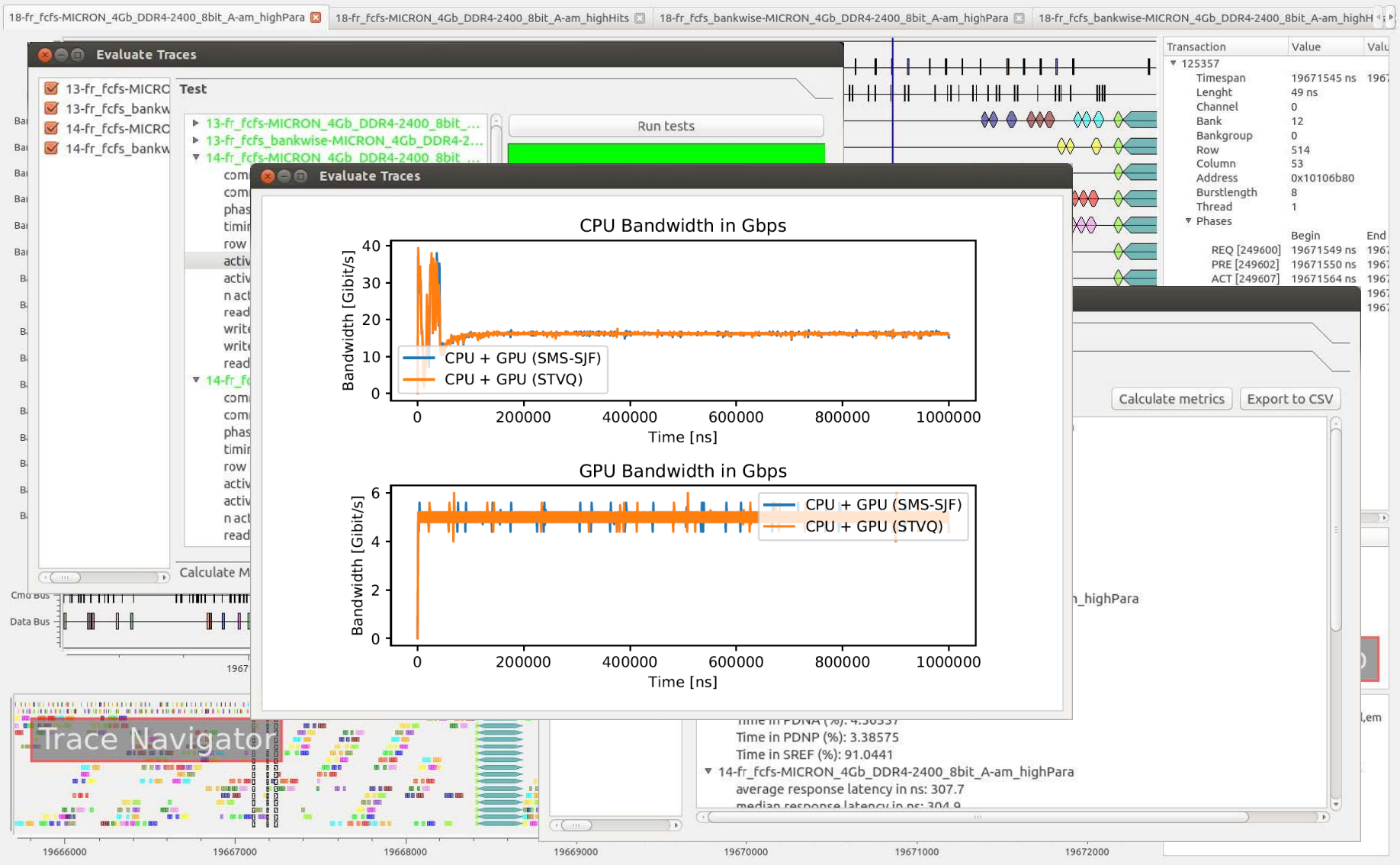
Coupling gem5 with DRAMSys Continued



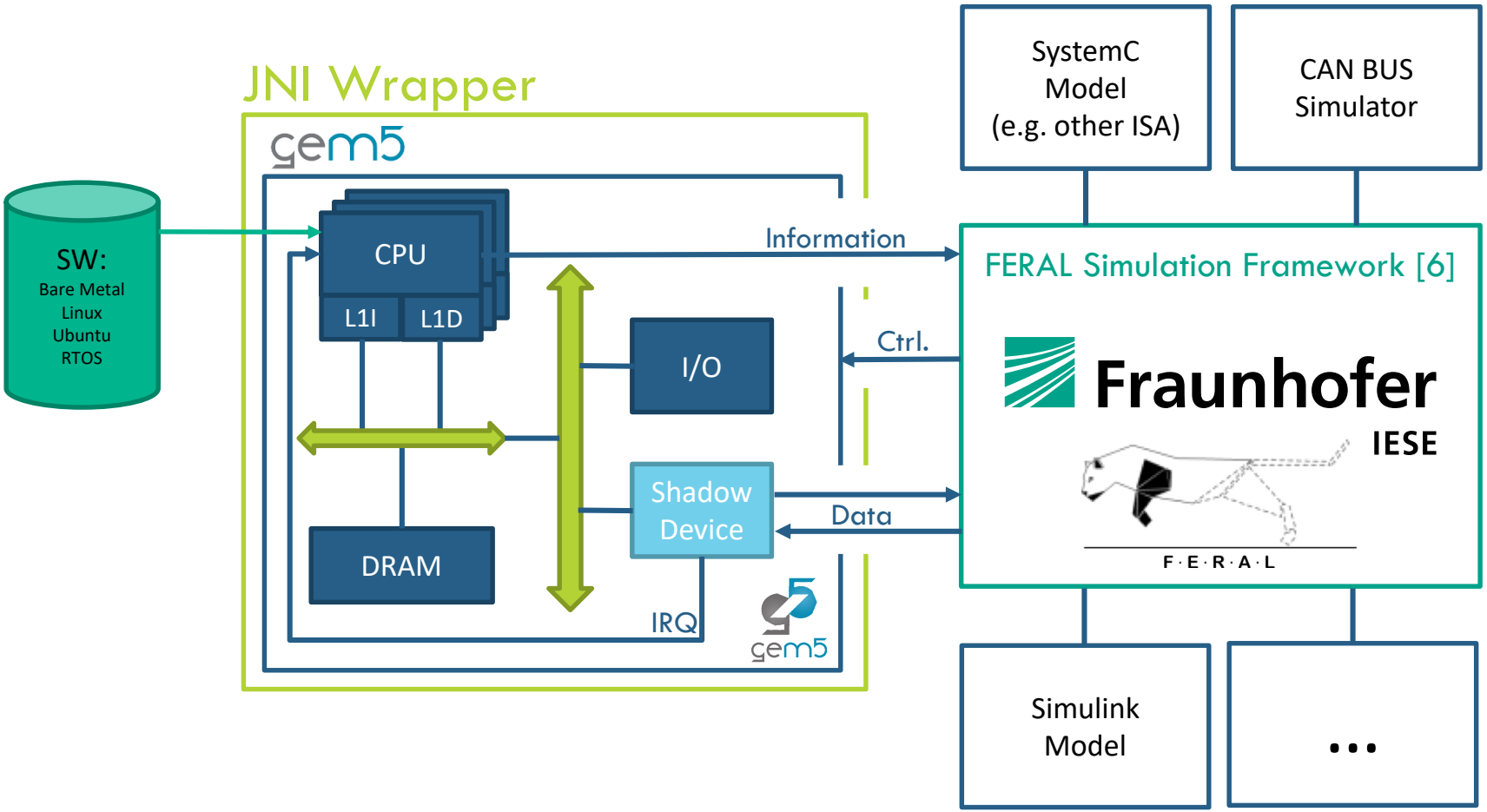
Coupling gem5 with DRAMSys Continued



Coupling gem5 with DRAMSys Continued



Connecting gem5 to Non-SystemC Simulators



Scenarios with FERAL

- Coupling of different Simulators with different models of computation (e.g. Simulink with gem5 or SystemC)
- gem5 compiled as C++ library and wrapped in JNI wrapper

- Development of software concepts
  - Simulation of systems of systems
  - Combining different levels of abstraction

- Software Testing:
  - Normal software testing instruments source code or binary → Intrusive
  - gem5 is instrumented instead
  - Supervised testing of concurrent software
  - Fault Injection
  - Coverage

Summary and Outlook

- Full interoperability between gem5 and SystemC
- Fully compliant to the SystemC standard
- It is part of the gem5 repository!

→ Next steps:

- → replace the entire simulation kernel and communication System by SystemC/TLM (?)
- → Remove step for .ini generation (?)
- → Suggestions? We are open!

Thank you!

References

[1] Christian Menard, Matthias Jung, Jeronimo Castrillon, Norbert Wehn, **"System Simulation with gem5 and SystemC: The Keystone for Full Interoperability"**, *Proceedings of the IEEE International Conference on Embedded Computer Systems Architectures Modeling and Simulation (SAMOS)*, Jul 2017.

[2] Marcus Völp, Sascha Klüppelholz, Jeronimo Castrillon, Hermann Härtig, et al. **"The Orchestration Stack: The Impossible Task of Designing Software for Unknown Future Post-CMOS Hardware"**, *Proceedings of the 1st International Workshop on Post-Moore's Era Supercomputing (PMES), Co-located with The International Conference for High Performance Computing, Networking, Storage and Analysis (SC16)*, Salt Lake City, USA, Nov 2016

[3] Matthias Jung, Christian Weis, Norbert Wehn, Karthik Chandrasekar, **"TLM Modelling of 3D Stacked Wide I/O DRAM Subsystems, A Virtual Platform for Memory Controller Design Space Exploration"** *Rapid Simulation and Performance Evaluation: Methods and Tools (RAPIDO)*, January, 2013, Berlin.

[4] Matthias Jung, Christian Weis, Norbert Wehn, **"DRAMSys: A flexible DRAM Subsystem Design Space Exploration Framework"**, *IPSJ Transactions on System LSI Design Methodology (T-SLDM)*, October, 2015.

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[6] Thomas Kuhn, Thomas Forster, Tobias Braun, Reinhard Gotzhein, **"FERAL - Framework for Simulator Coupling on Requirements and Architecture Level"**, *IEEE Computer Society: Eleventh ACM/IEEE International Conference on Formal Methods and Models for Codesign, MEMOCODE 2013*. Proceedings : 8-20 Oct. 2013, Portland, OR